An Introduction to Semidefinite Program Relaxations of Quadratically Constrained Quadratic Programs

Fatma Kılınç-Karzan

Carnegie Mellon University Tepper School of Business

IPCO Summer School

June 19-20, 2023

Convex optimization is accurate and efficient.

- Convex optimization is accurate and efficient.
- Unfortunately, many practical optimization problems are nonconvex.

- Convex optimization is accurate and efficient.
- Unfortunately, many practical optimization problems are nonconvex.
- Binary constraints, sparsity constraints, rank constraints...

- Convex optimization is accurate and efficient.
- Unfortunately, many practical optimization problems are nonconvex.
- Binary constraints, sparsity constraints, rank constraints...
- Generally hard

- Convex optimization is accurate and efficient.
- Unfortunately, many practical optimization problems are nonconvex.
- Binary constraints, sparsity constraints, rank constraints...
- Generally hard, but not always!

- Convex optimization is accurate and efficient.
- Unfortunately, many practical optimization problems are nonconvex.
- Binary constraints, sparsity constraints, rank constraints...
- Generally hard, but not always!
- Some nonconvex problems can be solved using convex optimization.

- Convex optimization is accurate and efficient.
- Unfortunately, many practical optimization problems are nonconvex.
- Binary constraints, sparsity constraints, rank constraints...
- Generally hard, but not always!
- Some nonconvex problems can be solved using convex optimization.
- Today and Tomorrow:

- Convex optimization is accurate and efficient.
- Unfortunately, many practical optimization problems are nonconvex.
- Binary constraints, sparsity constraints, rank constraints...
- Generally hard, but not always!
- Some nonconvex problems can be solved using convex optimization.
- Today and Tomorrow:
 - Examine quadratically constrained quadratic programs (QCQPs) and their semidefinite program (SDPs) relaxations,

- Convex optimization is accurate and efficient.
- Unfortunately, many practical optimization problems are nonconvex.
- Binary constraints, sparsity constraints, rank constraints...
- Generally hard, but not always!
- Some nonconvex problems can be solved using convex optimization.
- Today and Tomorrow:
 - Examine quadratically constrained quadratic programs (QCQPs) and their semidefinite program (SDPs) relaxations,
 - Understand structures within QCQPs that enable us to solve them via SDPs,

- Convex optimization is accurate and efficient.
- Unfortunately, many practical optimization problems are nonconvex.
- Binary constraints, sparsity constraints, rank constraints...
- Generally hard, but not always!
- Some nonconvex problems can be solved using convex optimization.
- Today and Tomorrow:
 - Examine quadratically constrained quadratic programs (QCQPs) and their semidefinite program (SDPs) relaxations,
 - Understand structures within QCQPs that enable us to solve them via SDPs,
 - Exploit structures governing exactness properties to design efficient first-order methods to solve a class of low rank SDPs.

• An introduction to SDPs

- An introduction to SDPs
- An introduction to QCQPs and their SDP relaxations

- An introduction to SDPs
- An introduction to QCQPs and their SDP relaxations

• Rank-one generated (ROG) property of SDPs

- An introduction to SDPs
- An introduction to QCQPs and their SDP relaxations

Rank-one generated (ROG) property of SDPs

Definition

- An introduction to SDPs
- An introduction to QCQPs and their SDP relaxations

• Rank-one generated (ROG) property of SDPs

- Definition
- Implications

- An introduction to SDPs
- An introduction to QCQPs and their SDP relaxations

• Rank-one generated (ROG) property of SDPs

- Definition
- Implications
- Examples

An introduction to SDPs

References:

Ben-Tal, A. and Nemirovski, A. (2001). *Lectures on Modern Convex Optimization*, volume 2 of *MPS-SIAM Ser. Optim.* SIAM

- $\mathbb{R}^n = \text{real column vectors of length } n$
- $\mathbb{R}^{m \times n}$ = real matrices of size $m \times n$
- $\mathbb{S}^n \subseteq \mathbb{R}^{n \times n}$ = space of $n \times n$ real symmetric matrices

- $\mathbb{R}^n = \text{real column vectors of length } n$
- $\mathbb{R}^{m \times n}$ = real matrices of size $m \times n$
- $\mathbb{S}^n \subseteq \mathbb{R}^{n \times n}$ = space of $n \times n$ real symmetric matrices
 - \implies Symmetry of the matrices ensures that the eigenvalues are *all* real.

• In \mathbb{R}^n , we use the *standard Euclidean inner product* given by

$$\langle x, y \rangle = \sum_{i \in [n]} x_i y_i$$

• In \mathbb{R}^n , we use the standard Euclidean inner product given by

$$\langle x, y \rangle = \sum_{i \in [n]} x_i y_i$$

and it induces the Euclidean norm: $||x||_2 := \sqrt{\sum_{i \in [n]} x_i^2}$.

• In \mathbb{R}^n , we use the standard Euclidean inner product given by

$$\langle x, y \rangle = \sum_{i \in [n]} x_i y_i$$

and it induces the *Euclidean norm*: $||x||_2 := \sqrt{\sum_{i \in [n]} x_i^2}$.

• In $\mathbb{R}^{m \times n}$, we use the *trace (Frobenius) inner product* given by

$$\langle X, Y \rangle = \sum_{i \in [m]} \sum_{j \in [n]} X_{ij} Y_{ij} = \operatorname{tr}(X^{\top}Y)$$

• In \mathbb{R}^n , we use the standard Euclidean inner product given by

$$\langle x, y \rangle = \sum_{i \in [n]} x_i y_i$$

and it induces the Euclidean norm: $\|x\|_2 := \sqrt{\sum_{i \in [n]} x_i^2}$.

• In $\mathbb{R}^{m \times n}$, we use the *trace (Frobenius) inner product* given by

$$\langle X, Y \rangle = \sum_{i \in [m]} \sum_{j \in [n]} X_{ij} Y_{ij} = \operatorname{tr}(X^{\top}Y)$$

and it induces the *Frobenius norm*: $||X||_2 := \sqrt{\langle X, X \rangle} = \sqrt{\sum_{i \in [m]} \sum_{j \in [n]} X_{ij}^2}$.

A matrix $X \in \mathbb{S}^n$ is positive semidefinite if and only if:

• $a^{\top}Xa \ge 0$ for all $a \in \mathbb{R}^n$

A matrix $X \in \mathbb{S}^n$ is positive semidefinite if and only if:

- $a^{\top}Xa \ge 0$ for all $a \in \mathbb{R}^n$
- $\lambda_{\min}(X) \ge 0$

A matrix $X \in \mathbb{S}^n$ is positive semidefinite if and only if:

- $a^{\top}Xa \ge 0$ for all $a \in \mathbb{R}^n$
- $\lambda_{\min}(X) \ge 0$
- $X = VV^{\top}$ for some $V \in \mathbb{R}^{n \times r}$ (note $\operatorname{rank}(X) \leq r$)

A matrix $X \in \mathbb{S}^n$ is positive semidefinite if and only if:

- $a^{\top}Xa \ge 0$ for all $a \in \mathbb{R}^n$
- $\lambda_{\min}(X) \ge 0$
- $X = VV^{\top}$ for some $V \in \mathbb{R}^{n \times r}$ (note $\operatorname{rank}(X) \leq r$)

In particular, $X = \sum_{k \in [r]} x_k x_k^\top$ where $x_k \in \mathbb{R}^n$ for all $k \in [r]$ where $\operatorname{rank}(X) \leq r$

A matrix $X \in \mathbb{S}^n$ is positive semidefinite if and only if:

- $a^{\top}Xa \ge 0$ for all $a \in \mathbb{R}^n$
- $\lambda_{\min}(X) \ge 0$
- $X = VV^{\top}$ for some $V \in \mathbb{R}^{n \times r}$ (note $\operatorname{rank}(X) \leq r$)

In particular, $X = \sum_{k \in [r]} x_k x_k^{\top}$ where $x_k \in \mathbb{R}^n$ for all $k \in [r]$ where $\operatorname{rank}(X) \leq r$

• every principle submatrix of X has nonnegative determinant

A matrix $X \in \mathbb{S}^n$ is positive semidefinite if and only if:

- $a^{\top}Xa \ge 0$ for all $a \in \mathbb{R}^n$
- $\lambda_{\min}(X) \ge 0$
- $X = VV^{\top}$ for some $V \in \mathbb{R}^{n \times r}$ (note $\operatorname{rank}(X) \leq r$)

In particular, $X = \sum_{k \in [r]} x_k x_k^{\top}$ where $x_k \in \mathbb{R}^n$ for all $k \in [r]$ where $\operatorname{rank}(X) \leq r$

• every principle submatrix of X has nonnegative determinant

A matrix $X \in \mathbb{S}^n$ is positive semidefinite if and only if:

- $a^{\top}Xa \ge 0$ for all $a \in \mathbb{R}^n$
- $\lambda_{\min}(X) \ge 0$
- $X = VV^{\top}$ for some $V \in \mathbb{R}^{n \times r}$ (note $\operatorname{rank}(X) \leq r$)

In particular, $X = \sum_{k \in [r]} x_k x_k^{\top}$ where $x_k \in \mathbb{R}^n$ for all $k \in [r]$ where $\operatorname{rank}(X) \leq r$

• every principle submatrix of X has nonnegative determinant

Notation

•
$$\mathbb{S}^n_+$$
 = set of $n \times n$ positive semidefinite matrices

•
$$X \in \mathbb{S}^n_+$$
, or $\displaystyle rac{X \succeq 0}{}$, or X is "PSD"

Important properties of \mathbb{S}^{n}_{+} :

• It is a *cone*!

Important properties of \mathbb{S}^n_+ :

- It is a *cone*!
- In fact it is a *proper*, i.e., closed, convex, pointed, full-dimensional, cone

Important properties of \mathbb{S}^n_+ :

- It is a *cone*!
- In fact it is a *proper*, i.e., closed, convex, pointed, full-dimensional, cone
- It is *self-dual*, i.e., $\{S \in \mathbb{S}^n : \langle S, X \rangle \ge 0, \forall X \in \mathbb{S}^n_+\} = \mathbb{S}^n_+$

Important properties of \mathbb{S}^n_+ :

- It is a cone!
- In fact it is a *proper*, i.e., closed, convex, pointed, full-dimensional, cone
- It is *self-dual*, i.e., $\{S \in \mathbb{S}^n : \langle S, X \rangle \ge 0, \forall X \in \mathbb{S}^n_+\} = \mathbb{S}^n_+$ In particular, $X, S \in \mathbb{S}^n_+ \implies \langle S, X \rangle \ge 0$
What is the dimension of \mathbb{S}^n_+ ?

What is the dimension of \mathbb{S}^n_+ ?

• Ambient dimension is n^2

What is the dimension of \mathbb{S}^{n}_{\perp} ?

- Ambient dimension is n^2

• But, symmetry takes away $\binom{n}{2}$ degrees of freedom

What is the dimension of \mathbb{S}^n_{\perp} ?

- Ambient dimension is n^2
- But, symmetry takes away $\binom{n}{2}$ degrees of freedom

• So, its dimension is $\binom{n+1}{2}$

When is a diagonal matrix in \mathbb{S}^{n}_{+} ?

$$D := \begin{pmatrix} D_{11} & 0 & \dots & 0 \\ 0 & D_{22} & \dots & 0 \\ & & \dots & \\ 0 & 0 & \dots & D_{nn} \end{pmatrix}$$

• *D* is a diagonal matrix where $diag(D) = (D_{11}, D_{22}, \dots, D_{nn})^{\top}$

When is a diagonal matrix in \mathbb{S}^{n}_{+} ?

$$D := \begin{pmatrix} D_{11} & 0 & \dots & 0\\ 0 & D_{22} & \dots & 0\\ & & \dots & \\ 0 & 0 & \dots & D_{nn} \end{pmatrix}$$

- *D* is a diagonal matrix where $diag(D) = (D_{11}, D_{22}, \dots, D_{nn})^{\top}$
- Its eigenvalues are $D_{11}, D_{22}, \ldots, D_{nn}$

When is a diagonal matrix in \mathbb{S}^{n}_{+} ?

$$D := \begin{pmatrix} D_{11} & 0 & \dots & 0 \\ 0 & D_{22} & \dots & 0 \\ & & \dots & \\ 0 & 0 & \dots & D_{nn} \end{pmatrix}$$

- *D* is a diagonal matrix where $diag(D) = (D_{11}, D_{22}, \dots, D_{nn})^{\top}$
- Its eigenvalues are $D_{11}, D_{22}, \ldots, D_{nn}$
- So, $D \in \mathbb{S}^n_+$ iff $\operatorname{diag}(D) \ge 0$

Is the following matrix in \mathbb{S}^3_+ ?

$$\begin{pmatrix} 1 & -1 & 0 \\ -1 & 1 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

Is the following matrix in \mathbb{S}^3_+ ?

$$\begin{pmatrix} 1 & -1 & 0 \\ -1 & 1 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

• Yes, we can check its principal minors...

Is the following matrix in \mathbb{S}^3_+ ?

$$\begin{pmatrix} 1 & -1 & 0 \\ -1 & 1 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

• Yes, we can check its principal minors...

• Also, note that it is equal to
$$vv^{\top}$$
 where $v = \begin{pmatrix} 1 \\ -1 \\ 0 \end{pmatrix}$

Is the following matrix in \mathbb{S}^3_+ ?

$$\begin{pmatrix} 9 & -3 & -6 \\ -3 & 1 & 2 \\ -6 & 2 & 4 \end{pmatrix}$$

Is the following matrix in \mathbb{S}^3_+ ?

$$\begin{pmatrix} 9 & -3 & -6 \\ -3 & 1 & 2 \\ -6 & 2 & 4 \end{pmatrix}$$

• Yes, because it is equal to vv^{\top} where $v = \begin{pmatrix} -3 \\ 1 \\ 2 \end{pmatrix}$

Theorem

- $X \in \mathbb{S}^n_+$ if and only if there exists
 - an orthogonal matrix $U \in \mathbb{R}^{n \times n}$, and
 - a nonnegative diagonal matrix $D \in \mathbb{S}^n$

such that $X = UDU^{\top}$.

Theorem

- $X \in \mathbb{S}^n_+$ if and only if there exists
 - an orthogonal matrix $U \in \mathbb{R}^{n \times n}$, and
 - a nonnegative diagonal matrix $D \in \mathbb{S}^n$

```
such that X = UDU^{\top}.
```

Here, the elements of $\underline{\operatorname{diag}(D)}$ are precisely the eigenvalues of X, and the columns of U are the corresponding eigenvectors of X.

Primal SDP problem:

$$\operatorname{Opt}(P) := \inf_{X \in \mathbb{S}^n} \left\{ \langle C, X \rangle : \begin{array}{cc} \langle A_i, X \rangle = b_i, & \forall i \in [m], \\ X \succeq 0 \end{array} \right\},$$

where

- the decision variable is $X \in \mathbb{S}^n$
- the data are the matrices $C, A_1, \ldots, A_m \in \mathbb{S}^n$, and the vector $b \in \mathbb{R}^m$

Specify the data for this problem:

$$\inf_{X \in \mathbb{S}^2} \left\{ \begin{array}{c} X_{11} + X_{22} = 1\\ X_{12} : & \begin{pmatrix} X_{11} & X_{12} \\ X_{12} & X_{22} \end{pmatrix} \succeq 0 \end{array} \right\}$$

Specify the data for this problem:

$$\inf_{X \in \mathbb{S}^2} \left\{ \begin{array}{c} X_{11} + X_{22} = 1\\ X_{12} : & \begin{pmatrix} X_{11} & X_{12} \\ X_{12} & X_{22} \end{pmatrix} \succeq 0 \end{array} \right\}$$

•
$$n = 2$$
 and $m = 1$
• $C = \frac{1}{2} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$ and $A_1 = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$
• $b_1 = 1$

$$Opt^* := \inf_{X \in \mathbb{S}^2} \left\{ \begin{array}{c} X_{11} + X_{22} = 1 \\ X_{12} : \begin{pmatrix} X_{11} & X_{12} \\ X_{12} & X_{22} \end{pmatrix} \succeq 0 \end{array} \right\}$$

$$Opt^* := \inf_{X \in \mathbb{S}^2} \left\{ \begin{aligned} X_{11} + X_{22} &= 1\\ X_{12} : & \begin{pmatrix} X_{11} & X_{12} \\ X_{12} & X_{22} \end{pmatrix} \succeq 0 \end{aligned} \right\}$$

$$Opt^* = \inf_{X_{11}, X_{22}, X_{12}} \left\{ \begin{array}{c} X_{11} + X_{22} = 1 \\ X_{12} : & X_{11} \ge 0, \ X_{22} \ge 0 \\ & X_{12}^2 \le X_{11} X_{22} \end{array} \right\}$$

$$Opt^* := \inf_{X \in \mathbb{S}^2} \left\{ \begin{aligned} X_{11} + X_{22} &= 1\\ X_{12} : & \begin{pmatrix} X_{11} & X_{12} \\ X_{12} & X_{22} \end{pmatrix} \succeq 0 \end{aligned} \right\}$$

$$Opt^* = \inf_{X_{11}, X_{22}, X_{12}} \left\{ \begin{array}{cc} X_{11} + X_{22} = 1 \\ X_{12} : & X_{11} \ge 0, \ X_{22} \ge 0 \\ & X_{12}^2 \le X_{11} X_{22} \end{array} \right\} \\ = \inf_{X_{11}, X_{12}} \left\{ \begin{array}{cc} X_{11} \ge 0, \ X_{11} \le 1 \\ X_{12} : & X_{12}^2 \le X_{11} (1 - X_{11}) \end{array} \right\}$$

$$Opt^* := \inf_{X \in \mathbb{S}^2} \left\{ \begin{array}{c} X_{11} + X_{22} = 1 \\ X_{12} : \begin{pmatrix} X_{11} & X_{12} \\ X_{12} & X_{22} \end{pmatrix} \succeq 0 \end{array} \right\}$$

$$\begin{aligned}
\text{Opt}^* &= \inf_{X_{11}, X_{22}, X_{12}} \left\{ \begin{array}{cc} X_{11} + X_{22} = 1 \\ X_{12} : & X_{11} \ge 0, \ X_{22} \ge 0 \\ & X_{12}^2 \le X_{11} X_{22} \end{array} \right\} \\
&= \inf_{X_{11}} \left\{ -\sqrt{X_{11}(1 - X_{11})} : \quad 0 \le X_{11} \le 1 \end{array} \right\} \\
\end{aligned}$$

$$Opt^* := \inf_{X \in \mathbb{S}^2} \left\{ \begin{array}{c} X_{11} + X_{22} = 1 \\ X_{12} : \begin{pmatrix} X_{11} & X_{12} \\ X_{12} & X_{22} \end{pmatrix} \succeq 0 \end{array} \right\}$$

$$\begin{array}{l}
\operatorname{Opt}^{*} = \inf_{X_{11}, X_{22}, X_{12}} \left\{ \begin{array}{c}
X_{11} + X_{22} = 1 \\
X_{12} : X_{11} \ge 0, \ X_{22} \ge 0 \\
X_{12}^{2} \le X_{11} X_{22}
\end{array} \right\} = \inf_{X_{11}, X_{12}} \left\{ X_{12} : \begin{array}{c}
X_{11} \ge 0, \ X_{11} \le 1 \\
X_{12}^{2} \le X_{11} (1 - X_{11})
\end{array} \right\} \\
= \inf_{X_{11}} \left\{ -\sqrt{X_{11}(1 - X_{11})} : 0 \le X_{11} \le 1 \right\}$$

$$Opt^* = -\frac{1}{2}$$
 and $X^* = \frac{1}{2} \begin{pmatrix} 1 & -1 \\ -1 & 1 \end{pmatrix}$

LP is a special case of SDP:

$$\inf_{x \in \mathbb{R}^n} \left\{ \langle c, x \rangle : \begin{array}{c} \langle a_i, x \rangle = b_i, \quad \forall i \in [m], \\ x \ge 0 \end{array} \right\} \\ \iff \inf_{X \in \mathbb{S}^n} \left\{ \langle \operatorname{Diag}(c), X \rangle : \begin{array}{c} \langle \operatorname{Diag}(a_i), X \rangle = b_i, \quad \forall i \in [m], \\ X \succeq 0 \end{array} \right\}$$

Second-order cone programs (SOCPs) are a special case of SDPs:

$$\|x\|_2 \le t \quad \Longleftrightarrow \quad \begin{pmatrix} t & x^\top \\ x & tI_n \end{pmatrix} \succeq 0$$

Second-order cone programs (SOCPs) are a special case of SDPs:

$$\|x\|_2 \le t \quad \Longleftrightarrow \quad \begin{pmatrix} t & x^\top \\ x & tI_n \end{pmatrix} \succeq 0$$

Second-order cone programs (SOCPs) are a special case of SDPs:

$$\|x\|_2 \le t \quad \Longleftrightarrow \quad \begin{pmatrix} t & x^\top \\ x & tI_n \end{pmatrix} \succeq 0$$

This is based on the following very useful result:

Theorem (Schur Complement Lemma) Consider a symmetric matrix $M := \begin{pmatrix} P & Q^T \\ Q & R \end{pmatrix}$ such that R is positive definite. Then, $M \succeq 0$ iff $P - Q^T R^{-1}Q \succeq 0$.

What can be expressed as an SDP?

Many nice functions of eigenvalues (or singular values) of matrices admit SDP representations...

What can be expressed as an SDP?

Many nice functions of eigenvalues (or singular values) of matrices admit SDP representations...

Theorem

- Let f: ℝⁿ → ℝ be a convex, SDP representable, permutation invariant function, i.e., f(x) = f(Px) for every permutation matrix P.
- Let $\lambda(X)$ denote the vector of eigenvalues of matrix $X \in \mathbb{S}^n$.

Then, the epigraph of the function $F(X) = f(\lambda(X)) : \mathbb{S}^n \to \mathbb{R}$ admits an SDP representation.

What can be expressed as an SDP?

Many nice functions of eigenvalues (or singular values) of matrices admit SDP representations...

Theorem

- Let f: ℝⁿ → ℝ be a convex, SDP representable, permutation invariant function, i.e., f(x) = f(Px) for every permutation matrix P.
- Let $\lambda(X)$ denote the vector of eigenvalues of matrix $X \in \mathbb{S}^n$.

Then, the epigraph of the function $F(X) = f(\lambda(X)) : \mathbb{S}^n \to \mathbb{R}$ admits an SDP representation.

•
$$\lambda_{\max}(X)$$
, $\sum_{i \in [n]} \lambda_i(X)$,
• $\|X\|_p \coloneqq \|\lambda(X)\|_p = \left(\sum_{i \in [n]} |\lambda_i(X)|^p\right)^{1/p}$ for $p \in \mathbb{Q}$ and $p \ge 1$,
• $-\log \det(X) = -\sum_{i \in [n]} \log(\lambda_i(X))$ for $X \succ 0, \ldots$

Conic problems and their duals

Consider the conic optimization problem is

$$Opt(P) := \inf_{X} \left\{ \langle C, X \rangle : \begin{array}{cc} \langle A_i, X \rangle = b_i, & \forall i \in [m], \\ X \in \mathbb{K} \end{array} \right\}.$$

where \mathbb{K} is a proper cone.

Conic problems and their duals

Consider the conic optimization problem is

$$Opt(P) := \inf_{X} \left\{ \langle C, X \rangle : \begin{array}{c} \langle A_i, X \rangle = b_i, \quad \forall i \in [m], \\ X \in \mathbb{K} \end{array} \right\}.$$

where \mathbb{K} is a proper cone.

Given a cone \mathbb{K} , define the dual cone as

$$\mathbb{K}_* := \left\{ \xi : \langle \xi, X \rangle \ge 0, \ \forall X \in \mathbb{K} \right\}.$$

Conic problems and their duals

Consider the conic optimization problem is

$$Opt(P) := \inf_{X} \left\{ \langle C, X \rangle : \begin{array}{c} \langle A_i, X \rangle = b_i, \quad \forall i \in [m], \\ X \in \mathbb{K} \end{array} \right\}.$$

where \mathbb{K} is a proper cone.

Given a cone \mathbb{K} , define the dual cone as

$$\mathbb{K}_* := \left\{ \xi: \ \langle \xi, X \rangle \ge 0, \ \forall X \in \mathbb{K} \right\}.$$

Then, the dual conic problem is given by

$$Opt(D) := \sup_{y \in \mathbb{R}^m, S} \left\{ \langle b, y \rangle : \begin{array}{c} \sum_{i \in [m]} A_i y_i + S = C, \\ S \in \mathbb{K}_* \end{array} \right\}$$

.

Conic duality

Theorem (Weak Duality Theorem)

- Let (*P*) and (*D*) be any pair of primal and dual conic programs, where the primal (*P*) is in minimization form.
- Let \bar{X} be a primal feasible solution, and (\bar{y},\bar{S}) be a dual feasible solution.

Then,

$$\langle C, \bar{X} \rangle - \langle b, \bar{y} \rangle = \langle \bar{S}, \bar{X} \rangle \ge 0.$$

Conic duality

Theorem (Weak Duality Theorem)

- Let (*P*) and (*D*) be any pair of primal and dual conic programs, where the primal (*P*) is in minimization form.
- Let \bar{X} be a primal feasible solution, and (\bar{y},\bar{S}) be a dual feasible solution.

Then,

$$\langle C, \bar{X} \rangle - \langle b, \bar{y} \rangle = \langle \bar{S}, \bar{X} \rangle \ge 0.$$

Proof.

Corollary (Weak Duality Theorem)

Let \bar{X} be a primal feasible solution to (P) (in minimization form), and (\bar{y}, \bar{S}) be a dual feasible solution to its dual (D). Then,

 $\langle C, \bar{X} \rangle \ge \operatorname{Opt}(P) \ge \operatorname{Opt}(D) \ge \langle b, \bar{y} \rangle$.

Corollary (Weak Duality Theorem)

Let \bar{X} be a primal feasible solution to (P) (in minimization form), and (\bar{y}, \bar{S}) be a dual feasible solution to its dual (D). Then,

 $\langle C, \bar{X} \rangle \ge \operatorname{Opt}(P) \ge \operatorname{Opt}(D) \ge \langle b, \bar{y} \rangle$.

Corollary

Let \bar{X} be a primal feasible solution to (P) (in minimization form), and (\bar{y}, \bar{S}) be a dual feasible solution to its dual (D). If $\langle C, \bar{X} \rangle = \langle b, \bar{y} \rangle$, then \bar{X} is primal optimum and (\bar{y}, \bar{S}) is dual optimum. Moreover, in the case of SDPs, $\langle \bar{X}, \bar{S} \rangle = 0$ iff $\bar{X}\bar{S} = 0$.
Dual SDP

Recall our primal SDP:

$$Opt(P) := \inf_{X \in \mathbb{S}^n} \left\{ \langle C, X \rangle : \begin{array}{cc} \langle A_i, X \rangle = b_i, & \forall i \in [m], \\ X \succeq 0 \end{array} \right\}.$$

Dual SDP

Recall our primal SDP:

$$Opt(P) := \inf_{X \in \mathbb{S}^n} \left\{ \langle C, X \rangle : \begin{array}{c} \langle A_i, X \rangle = b_i, \quad \forall i \in [m], \\ X \succeq 0 \end{array} \right\}.$$

Then, the dual SDP is given by

$$Opt(D) := \sup_{y \in \mathbb{R}^m, S \in \mathbb{S}^n} \left\{ \langle b, y \rangle : \sum_{\substack{i \in [m] \\ S \succeq 0}} A_i y_i + S = C, \\ S \succeq 0 \end{array} \right\}$$
$$= \sup_{y \in \mathbb{R}^m} \left\{ \langle b, y \rangle : C - \sum_{i \in [m]} A_i y_i \succeq 0 \right\}.$$

What is the dual of the following SDP?

$$\inf_{X \in \mathbb{S}^2} \left\{ \begin{array}{c} X_{11} + X_{22} = 1\\ X_{12} : & \begin{pmatrix} X_{11} & X_{12}\\ X_{12} & X_{22} \end{pmatrix} \succeq 0 \end{array} \right\}$$

• Dual SDP:
$$\operatorname{Opt}(D) = \sup_{y_1 \in \mathbb{R}} \left\{ y_1 : \begin{pmatrix} -y_1 & 1/2 \\ 1/2 & -y_1 \end{pmatrix} \succeq 0 \right\}$$

What is the dual of the following SDP?

$$\inf_{X \in \mathbb{S}^2} \left\{ \begin{array}{c} X_{11} + X_{22} = 1 \\ X_{12} : \begin{pmatrix} X_{11} & X_{12} \\ X_{12} & X_{22} \end{pmatrix} \succeq 0 \end{array} \right\}$$

• Dual SDP:
$$\operatorname{Opt}(D) = \sup_{y_1 \in \mathbb{R}} \left\{ y_1 : \begin{pmatrix} -y_1 & 1/2 \\ 1/2 & -y_1 \end{pmatrix} \succeq 0 \right\}$$

• $\operatorname{Opt}(D) = -\frac{1}{2}$

What is the dual of the following SDP?

$$\inf_{X \in \mathbb{S}^2} \left\{ \begin{array}{c} X_{11} + X_{22} = 1 \\ X_{12} : \begin{pmatrix} X_{11} & X_{12} \\ X_{12} & X_{22} \end{pmatrix} \succeq 0 \end{array} \right\}$$

• Dual SDP:
$$\operatorname{Opt}(D) = \sup_{y_1 \in \mathbb{R}} \left\{ y_1 : \begin{pmatrix} -y_1 & 1/2 \\ 1/2 & -y_1 \end{pmatrix} \succeq 0 \right\}$$

• $Opt(D) = -\frac{1}{2}$ • $y_1^* = -\frac{1}{2}$ and $S^* = \frac{1}{2} \begin{pmatrix} 1 & 1 \\ 1 & 1 \end{pmatrix}$

Let's verify...

$$X^* = \frac{1}{2} \begin{pmatrix} 1 & -1 \\ -1 & 1 \end{pmatrix}$$
 and $S^* = \frac{1}{2} \begin{pmatrix} 1 & 1 \\ 1 & 1 \end{pmatrix}$

Let's verify...

$$X^* = \frac{1}{2} \begin{pmatrix} 1 & -1 \\ -1 & 1 \end{pmatrix}$$
 and $S^* = \frac{1}{2} \begin{pmatrix} 1 & 1 \\ 1 & 1 \end{pmatrix}$

$$X^*S^* = \frac{1}{4} \begin{pmatrix} 1 & -1 \\ -1 & 1 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ 1 & 1 \end{pmatrix} = \begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix}$$

Do we always have strong duality, i.e., Opt(P) = Opt(D)?

SDP strong duality counter example

Consider

$$Opt(P) = \inf_{X \in \mathbb{S}^3} \left\{ \begin{aligned} X_{22} &= 0, \\ X_{11} : & X_{11} + 2X_{23} = 1, \\ & X \succeq 0 \end{aligned} \right\}$$

SDP strong duality counter example

Consider

$$Opt(P) = \inf_{X \in \mathbb{S}^3} \left\{ \begin{aligned} & X_{22} = 0, \\ X_{11} : & X_{11} + 2X_{23} = 1, \\ & X \succeq 0 \end{aligned} \right\}$$

and its dual

$$\operatorname{Opt}(D) = \sup_{y_1, y_2 \in \mathbb{R}} \left\{ -y_2 : \begin{pmatrix} 1+y_2 \\ y_1 & y_2 \\ y_2 \end{pmatrix} \succeq 0 \right\}$$

SDP strong duality counter example

Consider

$$Opt(P) = \inf_{X \in \mathbb{S}^3} \left\{ \begin{aligned} & X_{22} = 0, \\ X_{11} : & X_{11} + 2X_{23} = 1, \\ & X \succeq 0 \end{aligned} \right\}$$

$$\operatorname{Opt}(D) = \sup_{y_1, y_2 \in \mathbb{R}} \left\{ -y_2 : \begin{pmatrix} 1+y_2 \\ y_1 & y_2 \\ y_2 \end{pmatrix} \succeq 0 \right\}$$

•
$$Opt(P) = 1$$
 while $Opt(D) = 0$.

• Positive and finite duality gap ?!?!?!

Theorem (Strong conic duality)

Let (P) and (D) be a pair of feasible primal and dual conic programs, where the primal (P) is in minimization form.

- If \exists a primal feasible \bar{X} with $\bar{X} \in int(\mathbb{K})$ (i.e., primal strict feas. holds), then Opt(P) = Opt(D) and Opt(D) is attained.
- If \exists a dual feasible (\bar{y}, \bar{S}) with $\bar{S} \in int(\mathbb{K})$ (i.e., dual strict feas. holds), then Opt(P) = Opt(D) and Opt(P) is attained.
- If both primal and dual strict feas. hold, then \exists primal-dual optimal solutions $(\bar{X}, \bar{y}, \bar{S})$ s.t.

$$\operatorname{Opt}(P) = \langle C, \bar{X} \rangle = \langle b, \bar{y} \rangle = \operatorname{Opt}(D)$$
 (and for SDPs $\bar{X}\bar{S} = 0$).

A matrix $X \in \mathbb{S}^n$ is positive definite if and only if:

• $a^{\top}Xa > 0$ for all $a \in \mathbb{R}^n \setminus \{0\}$

A matrix $X \in \mathbb{S}^n$ is positive definite if and only if:

- $a^{\top}Xa > 0$ for all $a \in \mathbb{R}^n \setminus \{0\}$
- $\lambda_{\min}(X) > 0$

A matrix $X \in \mathbb{S}^n$ is positive definite if and only if:

- $a^{\top}Xa > 0$ for all $a \in \mathbb{R}^n \setminus \{0\}$
- $\lambda_{\min}(X) > 0$
- $X = VV^{\top}$ for some invertible $V \in \mathbb{R}^{n \times n}$ (note $\operatorname{rank}(X) = n$)

A matrix $X \in \mathbb{S}^n$ is positive definite if and only if:

- $a^{\top}Xa > 0$ for all $a \in \mathbb{R}^n \setminus \{0\}$
- $\lambda_{\min}(X) > 0$

• $X = VV^{\top}$ for some invertible $V \in \mathbb{R}^{n \times n}$ (note $\operatorname{rank}(X) = n$) In particular, $X = \sum_{k \in [n]} x_k x_k^{\top}$ where each $x_k \in \mathbb{R}^n$ is orthogonal to each x_j for all $k, j \in [n]$

A matrix $X \in \mathbb{S}^n$ is positive definite if and only if:

- $a^{\top}Xa > 0$ for all $a \in \mathbb{R}^n \setminus \{0\}$
- $\lambda_{\min}(X) > 0$

• $X = VV^{\top}$ for some invertible $V \in \mathbb{R}^{n \times n}$ (note $\operatorname{rank}(X) = n$) In particular, $X = \sum_{k \in [n]} x_k x_k^{\top}$ where each $x_k \in \mathbb{R}^n$ is orthogonal to each x_j for all $k, j \in [n]$

• every principle submatrix of X has positive determinant

A matrix $X \in \mathbb{S}^n$ is positive definite if and only if:

- $a^{\top}Xa > 0$ for all $a \in \mathbb{R}^n \setminus \{0\}$
- $\lambda_{\min}(X) > 0$

• $X = VV^{\top}$ for some invertible $V \in \mathbb{R}^{n \times n}$ (note $\operatorname{rank}(X) = n$) In particular, $X = \sum_{k \in [n]} x_k x_k^{\top}$ where each $x_k \in \mathbb{R}^n$ is orthogonal to each x_j for all $k, j \in [n]$

• every principle submatrix of X has positive determinant

A matrix $X \in \mathbb{S}^n$ is positive definite if and only if:

- $a^{\top}Xa > 0$ for all $a \in \mathbb{R}^n \setminus \{0\}$
- $\lambda_{\min}(X) > 0$

• $X = VV^{\top}$ for some invertible $V \in \mathbb{R}^{n \times n}$ (note $\operatorname{rank}(X) = n$) In particular, $X = \sum_{k \in [n]} x_k x_k^{\top}$ where each $x_k \in \mathbb{R}^n$ is orthogonal to each x_j for all $k, j \in [n]$

every principle submatrix of X has positive determinant

Notation

•
$$\mathbb{S}_{++}^n =$$
 set of $n \times n$ positive definite matrices

•
$$X \in \mathbb{S}^n_{++}$$
, or $rac{X \succ 0}{,}$ or X is "PD"

Remark

- Be careful about strict feasibility and attainment conditions when applying conic duality!
- Papers (especially the ones focusing on algorithms) often assume that both (*P*) and (*D*) have nonempty interior. But, it is best to double check in any given application!

$$-\sqrt{5} = \inf_{X \in \mathbb{S}^2} \left\{ \left\langle \begin{pmatrix} 1 & 2\\ 2 & -1 \end{pmatrix}, X \right\rangle : \begin{array}{c} \operatorname{tr}(X) = 1, \\ X \succeq 0 \end{array} \right\}$$

• Even if the data is rational, an SDP may have an irrational optimum solution: e.g.,

$$-\sqrt{5} = \inf_{X \in \mathbb{S}^2} \left\{ \left\langle \begin{pmatrix} 1 & 2\\ 2 & -1 \end{pmatrix}, X \right\rangle : \begin{array}{c} \operatorname{tr}(X) = 1, \\ X \succeq 0 \end{array} \right\}$$

• By specifying a tolerance $\epsilon > 0$, we seek an ϵ -optimal primal (or dual) solution.

$$-\sqrt{5} = \inf_{X \in \mathbb{S}^2} \left\{ \left\langle \begin{pmatrix} 1 & 2\\ 2 & -1 \end{pmatrix}, X \right\rangle : \begin{array}{c} \operatorname{tr}(X) = 1, \\ X \succeq 0 \end{array} \right\}$$

- By specifying a tolerance $\epsilon > 0$, we seek an ϵ -optimal primal (or dual) solution.
- Theoretically, ellipsoid algorithm is applicable (under strict feasibility assumptions) and guarantees $\approx O(m^2 \log(1/\epsilon))$ iterations to return an ϵ -optimal solution to (D), where each iteration requires $O(m^2 + mn^2 + n^3)$ floating point operations.

$$-\sqrt{5} = \inf_{X \in \mathbb{S}^2} \left\{ \left\langle \begin{pmatrix} 1 & 2\\ 2 & -1 \end{pmatrix}, X \right\rangle : \begin{array}{c} \operatorname{tr}(X) = 1, \\ X \succeq 0 \end{array} \right\}$$

- By specifying a tolerance $\epsilon > 0$, we seek an ϵ -optimal primal (or dual) solution.
- Theoretically, ellipsoid algorithm is applicable (under strict feasibility assumptions) and guarantees $\approx O(m^2 \log(1/\epsilon))$ iterations to return an ϵ -optimal solution to (D), where each iteration requires $O(m^2 + mn^2 + n^3)$ floating point operations.
- Modern (primal-dual) interior point methods do much better in practice...

$$-\sqrt{5} = \inf_{X \in \mathbb{S}^2} \left\{ \left\langle \begin{pmatrix} 1 & 2\\ 2 & -1 \end{pmatrix}, X \right\rangle : \begin{array}{c} \operatorname{tr}(X) = 1, \\ X \succeq 0 \end{array} \right\}$$

- By specifying a tolerance $\epsilon > 0$, we seek an ϵ -optimal primal (or dual) solution.
- Theoretically, ellipsoid algorithm is applicable (under strict feasibility assumptions) and guarantees $\approx O(m^2 \log(1/\epsilon))$ iterations to return an ϵ -optimal solution to (D), where each iteration requires $O(m^2 + mn^2 + n^3)$ floating point operations.
- Modern (primal-dual) interior point methods do much better in practice...
- For software package, Mosek has a very reliable implementation based on a specific P-D interior point method.

$$-\sqrt{5} = \inf_{X \in \mathbb{S}^2} \left\{ \left\langle \begin{pmatrix} 1 & 2\\ 2 & -1 \end{pmatrix}, X \right\rangle : \begin{array}{c} \operatorname{tr}(X) = 1, \\ X \succeq 0 \end{array} \right\}$$

- By specifying a tolerance $\epsilon > 0$, we seek an ϵ -optimal primal (or dual) solution.
- Theoretically, ellipsoid algorithm is applicable (under strict feasibility assumptions) and guarantees $\approx O(m^2 \log(1/\epsilon))$ iterations to return an ϵ -optimal solution to (D), where each iteration requires $O(m^2 + mn^2 + n^3)$ floating point operations.
- Modern (primal-dual) interior point methods do much better in practice...
- For software package, Mosek has a very reliable implementation based on a specific P-D interior point method.
- More on solving SDPs tomorrow...

An introduction to QCQPs

$$\begin{aligned} \text{Opt} &\coloneqq \inf_{x \in \mathbb{R}^n} \left\{ q_{\mathsf{obj}}(x) : \, q_i(x) \leq 0, \, \forall i \in [m] \right\} \\ q_i(x) &= x^\top A_i x + 2b_i^\top x + c_i \end{aligned}$$

$$\begin{aligned} \text{Opt} &\coloneqq \inf_{x \in \mathbb{R}^n} \left\{ q_{\mathsf{obj}}(x) : \, q_i(x) \leq 0, \, \forall i \in [m] \right\} \\ q_i(x) &= x^\top A_i x + 2b_i^\top x + c_i \end{aligned}$$

$$\begin{aligned} \text{Opt} &\coloneqq \inf_{x \in \mathbb{R}^n} \left\{ q_{\text{obj}}(x) : \, q_i(x) \leq 0, \, \forall i \in [m] \right\} \\ q_i(x) &= x^\top A_i x + 2b_i^\top x + c_i \end{aligned}$$



• $q_{\text{obj}}, q_1, \dots, q_m : \mathbb{R}^n \to \mathbb{R}$ quadratic (possibly nonconvex!)

$$\begin{aligned} \text{Opt} &\coloneqq \inf_{x \in \mathbb{R}^n} \left\{ q_{\mathsf{obj}}(x) : \, q_i(x) \leq 0, \, \forall i \in [m] \right\} \\ q_i(x) &= x^\top A_i x + 2b_i^\top x + c_i \end{aligned}$$



• Highly expressive:

$$\begin{aligned} \text{Opt} &\coloneqq \inf_{x \in \mathbb{R}^n} \left\{ q_{\mathsf{obj}}(x) : \, q_i(x) \leq 0, \, \forall i \in [m] \right\} \\ &q_i(x) = x^\top A_i x + 2b_i^\top x + c_i \end{aligned}$$



- Highly expressive:
 - optimization (MAX-CUT, MAX-CLIQUE,...)

$$Opt := \inf_{x \in \mathbb{R}^n} \left\{ q_{\mathsf{obj}}(x) : q_i(x) \le 0, \, \forall i \in [m] \right\}$$
$$q_i(x) = x^\top A_i x + 2b_i^\top x + c_i$$



- Highly expressive:
 - optimization (MAX-CUT, MAX-CLIQUE,...), control, ML+statistics (clustering, sparse regression,...)

$$Opt := \inf_{x \in \mathbb{R}^n} \left\{ q_{\mathsf{obj}}(x) : q_i(x) \le 0, \, \forall i \in [m] \right\}$$

$$q_i(x) = x^\top A_i x + 2b_i^\top x + c_i$$



- Highly expressive:
 - optimization (MAX-CUT, MAX-CLIQUE,...), control, ML+statistics (clustering, sparse regression,...)
 - **binary programs** $x_1(1-x_1) = 0$

$$Opt := \inf_{x \in \mathbb{R}^n} \left\{ q_{\mathsf{obj}}(x) : q_i(x) \le 0, \, \forall i \in [m] \right\}$$

$$q_i(x) = x^\top A_i x + 2b_i^\top x + c_i$$



- Highly expressive:
 - optimization (MAX-CUT, MAX-CLIQUE,...), control, ML+statistics (clustering, sparse regression,...)
 - **binary programs** $x_1(1-x_1) = 0$
 - polynomial optimization problems $x_1x_2 = z_{12}$
Quadratically constrained quadratic programs (QCQPs)

• $q_{\text{obj}}, q_1, \dots, q_m : \mathbb{R}^n \to \mathbb{R}$ quadratic (possibly nonconvex!)

$$Opt := \inf_{x \in \mathbb{R}^n} \left\{ q_{\mathsf{obj}}(x) : q_i(x) \le 0, \, \forall i \in [m] \right\}$$

$$q_i(x) = x^\top A_i x + 2b_i^\top x + c_i$$



- Highly expressive:
 - optimization (MAX-CUT, MAX-CLIQUE,...), control, ML+statistics (clustering, sparse regression,...)
 - **binary programs** $x_1(1-x_1) = 0$
 - polynomial optimization problems $x_1x_2 = z_{12}$
- NP-hard in general

•
$$q_i(x) \coloneqq x^\top A_i x + 2b_i^\top x + c_i$$

•
$$q_i(x) \coloneqq x^\top A_i x + 2b_i^\top x + c_i = \begin{pmatrix} x \\ 1 \end{pmatrix}^\top \begin{pmatrix} A_i & b_i \\ b_i^\top & c_i \end{pmatrix} \begin{pmatrix} x \\ 1 \end{pmatrix}$$

•
$$q_i(x) \coloneqq x^\top A_i x + 2b_i^\top x + c_i = \begin{pmatrix} x \\ 1 \end{pmatrix}^\top \underbrace{\begin{pmatrix} A_i & b_i \\ b_i^\top & c_i \end{pmatrix}}_{=: M_i} \begin{pmatrix} x \\ 1 \end{pmatrix}$$

•
$$q_i(x) \coloneqq x^\top A_i x + 2b_i^\top x + c_i = \begin{pmatrix} x \\ 1 \end{pmatrix}^\top \underbrace{\begin{pmatrix} A_i & b_i \\ b_i^\top & c_i \end{pmatrix}}_{=:M_i} \begin{pmatrix} x \\ 1 \end{pmatrix} = \left\langle M_i, \begin{pmatrix} xx^\top & x \\ x^\top & 1 \end{pmatrix} \right\rangle$$

•
$$q_i(x) := x^\top A_i x + 2b_i^\top x + c_i = \begin{pmatrix} x \\ 1 \end{pmatrix}^\top \underbrace{\begin{pmatrix} A_i & b_i \\ b_i^\top & c_i \end{pmatrix}}_{=:M_i} \begin{pmatrix} x \\ 1 \end{pmatrix} = \left\langle M_i, \begin{pmatrix} xx^\top & x \\ x^\top & 1 \end{pmatrix} \right\rangle$$

$$\bullet \qquad \qquad \mathbf{Opt} = \inf_{x \in \mathbb{R}^n} \left\{ \left\langle M_{\mathsf{obj}}, \begin{pmatrix} xx^\top & x \\ x^\top & 1 \end{pmatrix} \right\rangle : \ \left\langle M_i, \begin{pmatrix} xx^\top & x \\ x^\top & 1 \end{pmatrix} \right\rangle \le 0, \, \forall i \in [m] \right\}$$

•
$$q_i(x) \coloneqq x^\top A_i x + 2b_i^\top x + c_i = \begin{pmatrix} x \\ 1 \end{pmatrix}^\top \underbrace{\begin{pmatrix} A_i & b_i \\ b_i^\top & c_i \end{pmatrix}}_{=:M_i} \begin{pmatrix} x \\ 1 \end{pmatrix} = \left\langle M_i, \begin{pmatrix} xx^\top & x \\ x^\top & 1 \end{pmatrix} \right\rangle$$

$$\begin{aligned} \bullet \qquad \mathbf{Opt} &= \inf_{x \in \mathbb{R}^n} \left\{ \left\langle M_{\mathsf{obj}}, \begin{pmatrix} xx^\top & x \\ x^\top & 1 \end{pmatrix} \right\rangle : \ \left\langle M_i, \begin{pmatrix} xx^\top & x \\ x^\top & 1 \end{pmatrix} \right\rangle \leq 0, \ \forall i \in [m] \right\} \\ &\geq \inf_{x \in \mathbb{R}^n, \ X \in \mathbb{S}^n, \ Z \in \mathbb{S}^{n+1}} \left\{ \left\langle M_{\mathsf{obj}}, Z \right\rangle : \ Z = \begin{pmatrix} X \\ x^\top & 1 \end{pmatrix} \succeq 0 \right\} = \mathbf{Opt}_{\mathsf{SDP}} \end{aligned}$$

• QCQPs are highly expressive but NP-hard in general

- QCQPs are highly expressive but NP-hard in general
- Use SDP to get tractable convex relaxation

- QCQPs are highly expressive but NP-hard in general
- Use SDP to get tractable convex relaxation
- Vast literature on approximation guarantees: MAX-CUT, Nesterov's $\pi/2$, Matrix Cube, . . .

- QCQPs are highly expressive but NP-hard in general
- Use SDP to get tractable convex relaxation
- Vast literature on approximation guarantees: MAX-CUT, Nesterov's $\pi/2$, Matrix Cube, . . .
- NP-hard to decide $\operatorname{Opt} \stackrel{?}{=} \operatorname{Opt}_{\text{SDP}}$

[Laurent and Poljak, 1995]

- QCQPs are highly expressive but NP-hard in general
- Use SDP to get tractable convex relaxation
- Vast literature on approximation guarantees: MAX-CUT, Nesterov's $\pi/2$, Matrix Cube, . . .

• NP-hard to decide Opt
$$\stackrel{?}{=}$$
 Opt_{SDP}

[Laurent and Poljak, 1995]

 Interested in sufficient (and perhaps also necessary) conditions for SDP exactness.

• What does exactness mean?

- What does exactness mean?
 - Objective value exactness: $Opt = Opt_{SDP}$

- What does exactness mean?
 - Objective value exactness: $Opt = Opt_{SDP}$
 - Optimizer exactness: $\operatorname{arg\,min}\operatorname{Opt} = \operatorname{arg\,min}\operatorname{Opt}_{\mathsf{SDP}}$

- What does exactness mean?
 - Objective value exactness: $Opt = Opt_{SDP}$
 - Optimizer exactness: $\operatorname{arg\,min}\operatorname{Opt} = \operatorname{arg\,min}\operatorname{Opt}_{\mathsf{SDP}}$
 - Convex hull exactness: $\operatorname{conv}(\mathcal{D}) = \mathcal{D}_{SDP}$

- What does exactness mean?
 - Objective value exactness: $Opt = Opt_{SDP}$
 - Optimizer exactness: $\arg \min Opt = \arg \min Opt_{SDP}$
 - Convex hull exactness: $conv(\mathcal{D}) = \mathcal{D}_{SDP} \leftarrow convexification of substructures$

- What does exactness mean?
 - Objective value exactness: $Opt = Opt_{SDP}$
 - Optimizer exactness: $\arg \min Opt = \arg \min Opt_{SDP}$
 - Convex hull exactness: $conv(D) = D_{SDP} \leftarrow convexification of substructures$



- What does exactness mean?
 - Objective value exactness: $Opt = Opt_{SDP}$
 - Optimizer exactness: $\arg \min Opt = \arg \min Opt_{SDP}$
 - Convex hull exactness: $conv(D) = D_{SDP} \leftarrow convexification of substructures$



- What does exactness mean?
 - Objective value exactness: $Opt = Opt_{SDP}$
 - Optimizer exactness: $\arg \min Opt = \arg \min Opt_{SDP}$
 - Convex hull exactness: $conv(D) = D_{SDP} \leftarrow convexification of substructures$



- What does exactness mean?
 - Objective value exactness: $Opt = Opt_{SDP}$
 - Optimizer exactness: $\arg \min Opt = \arg \min Opt_{SDP}$
 - Convex hull exactness: $conv(D) = D_{SDP} \leftarrow convexification of substructures$



- What does exactness mean?
 - Objective value exactness: $Opt = Opt_{SDP}$
 - Optimizer exactness: $\arg \min Opt = \arg \min Opt_{SDP}$
 - Convex hull exactness: $conv(D) = D_{SDP} \leftarrow convexification of substructures$



- What does exactness mean?
 - Objective value exactness: $Opt = Opt_{SDP}$
 - Optimizer exactness: $\arg \min Opt = \arg \min Opt_{SDP}$
 - Convex hull exactness: $conv(D) = D_{SDP} \leftarrow convexification of substructures$



- What does exactness mean?
 - Objective value exactness: $Opt = Opt_{SDP}$
 - Optimizer exactness: $\arg \min Opt = \arg \min Opt_{SDP}$
 - Convex hull exactness: $conv(D) = D_{SDP} \leftarrow convexification of substructures$



- What does exactness mean?
 - Objective value exactness: $Opt = Opt_{SDP}$
 - Optimizer exactness: $\operatorname{arg\,min}\operatorname{Opt} = \operatorname{arg\,min}\operatorname{Opt}_{\mathsf{SDP}}$
 - Convex hull exactness: $conv(D) = D_{SDP} \leftarrow convexification of substructures$
 - Rank-one generated (ROG) property:

"SDP exactness that is oblivious to the objective function"

- What does exactness mean?
 - Objective value exactness: $Opt = Opt_{SDP}$
 - Optimizer exactness: $\operatorname{arg\,min}\operatorname{Opt} = \operatorname{arg\,min}\operatorname{Opt}_{\mathsf{SDP}}$
 - Convex hull exactness: $conv(D) = D_{SDP} \leftarrow convexification of substructures$
 - Rank-one generated (ROG) property:

"SDP exactness that is oblivious to the objective function"

 \longrightarrow exactness in the lifted SDP space

Exactness in the lifted SDP space: ROG property

References:

Argue, C., K.-K., F., and Wang, A. L. (2022+). Necessary and sufficient conditions for rank-one generated cones. *Math. Oper. Res.*, Forthcoming, (arXiv:2007.07433)

K.-K., F. and Wang, A. L. (2021). Exactness in SDP relaxations of QCQPs: Theory and applications. Tut. in Oper. Res. INFORMS

• Given $\mathcal{M} \subseteq \mathbb{S}^{n+1}$, define $\mathcal{S}(\mathcal{M}) \coloneqq \{Z \in \mathbb{S}^{n+1}_+ : \langle M, Z \rangle \le 0, \forall M \in \mathcal{M}\}$

• Given
$$\mathcal{M} \subseteq \mathbb{S}^{n+1}$$
, define $\mathcal{S}(\mathcal{M}) \coloneqq \{Z \in \mathbb{S}^{n+1}_+ : \langle M, Z \rangle \leq 0, \forall M \in \mathcal{M}\}$

Definition

A closed cone $S \subseteq \mathbb{S}^{n+1}_+$ is rank-one generated (ROG) if

$$\mathcal{S} = \operatorname{conv}\left(\mathcal{S} \cap \left\{zz^{\top} : z \in \mathbb{R}^{n+1}\right\}\right).$$

Equivalently, if all extreme rays are generated by rank-one matrices.

• Given
$$\mathcal{M} \subseteq \mathbb{S}^{n+1}$$
, define $\mathcal{S}(\mathcal{M}) \coloneqq \{Z \in \mathbb{S}^{n+1}_+ : \langle M, Z \rangle \leq 0, \forall M \in \mathcal{M}\}$

Definition

A closed cone $S \subseteq \mathbb{S}^{n+1}_+$ is rank-one generated (ROG) if

$$\mathcal{S} = \operatorname{conv}\left(\mathcal{S} \cap \left\{zz^{\top} : z \in \mathbb{R}^{n+1}\right\}\right).$$

Equivalently, if all extreme rays are generated by rank-one matrices.

• Analogy: (Integer programs, integral polyhedra) \approx (QCQPs, ROG)

Motivation: ROG \implies exactness

$$\begin{aligned} \text{For any } \mathcal{M} \subseteq \mathbb{S}^{n+1}, \quad \text{Opt} &= \inf_{x \in \mathbb{R}^n} \left\{ \begin{pmatrix} x \\ 1 \end{pmatrix}^\top M_{\text{obj}} \begin{pmatrix} x \\ 1 \end{pmatrix} : \quad \begin{pmatrix} x \\ 1 \end{pmatrix} \begin{pmatrix} x \\ 1 \end{pmatrix}^\top \in \mathcal{S}(\mathcal{M}) \right\} \\ &\geq \inf_{Z \in \mathbb{S}^{n+1}} \left\{ \langle M_{\text{obj}}, Z \rangle : \begin{array}{c} Z \in \mathcal{S}(\mathcal{M}) \\ \langle e_{n+1}e_{n+1}^\top, Z \rangle = 1 \end{array} \right\} = \text{Opt}_{\text{SDP}} \,. \end{aligned}$$

Motivation: ROG \implies exactness

$$\begin{split} \text{For any } \mathcal{M} \subseteq \mathbb{S}^{n+1}, \quad \text{Opt} &= \inf_{x \in \mathbb{R}^n} \left\{ \begin{pmatrix} x \\ 1 \end{pmatrix}^\top M_{\text{obj}} \begin{pmatrix} x \\ 1 \end{pmatrix} : \quad \begin{pmatrix} x \\ 1 \end{pmatrix} \begin{pmatrix} x \\ 1 \end{pmatrix} \begin{pmatrix} x \\ 1 \end{pmatrix}^\top \in \mathcal{S}(\mathcal{M}) \\ &\geq \inf_{Z \in \mathbb{S}^{n+1}} \left\{ \langle M_{\text{obj}}, Z \rangle : \begin{array}{c} Z \in \mathcal{S}(\mathcal{M}) \\ \langle e_{n+1} e_{n+1}^\top, Z \rangle = 1 \end{array} \right\} = \text{Opt}_{\text{SDP}} \,. \end{split}$$

• $\mathcal{S}(\mathcal{M})$ is ROG \implies objective value exactness.

Proposition

•
$$S(\mathcal{M})$$
 is ROG iff for all $M_{\mathsf{obj}} \in \mathbb{S}^{n+1}$,

$$\inf_{z \in \mathbb{R}^{n+1}} \left\{ \left\langle M_{\mathsf{obj}}, zz^{\top} \right\rangle : \, zz^{\top} \in \mathcal{S}(\mathcal{M}) \right\} = \inf_{Z \in \mathbb{S}^{n+1}} \left\{ \left\langle M_{\mathsf{obj}}, Z \right\rangle : \, Z \in \mathcal{S}(\mathcal{M}) \right\}.$$

• If
$$\mathcal{S}(\mathcal{M})$$
 is ROG, then for all $B, M_{\mathsf{obj}} \in \mathbb{S}^{n+1}$ s.t. $\operatorname{Opt}_{\mathsf{SDP}} > -\infty$,

$$\inf_{z \in \mathbb{R}^{n+1}} \left\{ \left\langle M_{\mathsf{obj}}, zz^{\top} \right\rangle : \frac{zz^{\top} \in \mathcal{S}(\mathcal{M})}{\left\langle B, zz^{\top} \right\rangle = 1} \right\} = \inf_{Z \in \mathbb{S}^{n+1}} \left\{ \left\langle M_{\mathsf{obj}}, Z \right\rangle : \frac{Z \in \mathcal{S}(\mathcal{M})}{\left\langle B, Z \right\rangle = 1} \right\}.$$

Related: Hildebrand [2016, Lemma 1.2]

Motivation: ROG \implies exactness

$$\begin{split} \text{For any } \mathcal{M} \subseteq \mathbb{S}^{n+1}, \quad \text{Opt} &= \inf_{x \in \mathbb{R}^n} \left\{ \begin{pmatrix} x \\ 1 \end{pmatrix}^\top M_{\text{obj}} \begin{pmatrix} x \\ 1 \end{pmatrix} : \quad \begin{pmatrix} x \\ 1 \end{pmatrix} \begin{pmatrix} x \\ 1 \end{pmatrix} \begin{pmatrix} x \\ 1 \end{pmatrix}^\top \in \mathcal{S}(\mathcal{M}) \\ &\geq \inf_{Z \in \mathbb{S}^{n+1}} \left\{ \langle M_{\text{obj}}, Z \rangle : \quad \begin{array}{c} Z \in \mathcal{S}(\mathcal{M}) \\ \langle e_{n+1} e_{n+1}^\top, Z \rangle = 1 \end{array} \right\} = \text{Opt}_{\text{SDP}} \,. \end{split}$$

• $S(\mathcal{M})$ is ROG \implies objective value exactness.

• $\mathcal{S}(\mathcal{M})$ is ROG \implies closed convex hull exactness via projected SDP set.

Theorem

Given
$$\mathcal{M} = [m]$$
, let $\mathcal{X} := \left\{ x \in \mathbb{R}^n : \begin{pmatrix} x \\ 1 \end{pmatrix} \begin{pmatrix} x \\ 1 \end{pmatrix} \begin{pmatrix} x \end{pmatrix}^\top \in \mathcal{S}(\mathcal{M}) \right\}$. and $A(\gamma^*) := \sum_{i \in [m]} \gamma_i^* A_i$.

• If $\mathcal{S}(\mathcal{M})$ is ROG and $\exists \gamma^* \in \mathbb{R}^m_+$ s.t. $A(\gamma^*) \succ 0$, then $\operatorname{conv}(\mathcal{X}) = \operatorname{projected} \operatorname{SDP}$ domain, i.e.,

$$\operatorname{conv}(\mathcal{X}) = \left\{ x \in \mathbb{R}^n : \begin{array}{l} \exists X, Z \text{ s.t. } Z = \begin{pmatrix} X & x \\ x^\top & 1 \end{pmatrix} \\ Z \in \mathcal{S}(\mathcal{M}) \end{array} \right\}$$

• If $\mathcal{S}(\mathcal{M})$ is ROG and $\exists \gamma^* \in \mathbb{R}^m_+$ s.t. $A_{\mathsf{obj}} + A(\gamma^*) \succ 0$, then

$$\operatorname{cl\,conv}\left(\left\{(x,t)\in\mathbb{R}^{n+1}:\ q_{\operatorname{obj}}(x)\leq t\ ,\ x\in\mathcal{X}\right\}\right)=\operatorname{cl}(\mathcal{D}_{\operatorname{SDP}}).$$

Applications

Exactness

- objective value and convex hull exactness
- variants of the S-lemma
- minimizing a *ratio* of quadratic functions

Applications

Exactness

- objective value and convex hull exactness
- variants of the S-lemma
- minimizing a ratio of quadratic functions
- Applications when $|\mathcal{M}|$ is finite
 - PSD matrix completion

[Grone et al., 1984], [Agler et al., 1988], [Paulsen et al., 1989]

Statistics applications + real algebraic geometry view [Hildebrand, 2016], [Blekherman et al., 2017]

Applications

Exactness

- objective value and convex hull exactness
- variants of the S-lemma
- minimizing a ratio of quadratic functions
- Applications when $|\mathcal{M}|$ is finite
 - PSD matrix completion

[Grone et al., 1984], [Agler et al., 1988], [Paulsen et al., 1989]

• Statistics applications + real algebraic geometry view [Hildebrand, 2016], [Blekherman et al., 2017]

\bullet Applications when $|\mathcal{M}|$ is not finite

- Trust-region subproblem and its variants [Sturm and Zhang, 2003], [Burer, 2015] and references therein, [Yang et al., 2018]
- Intersection of two Euclidean balls

[Kelly et al., 2022, Burer, 2023]
$$\mathcal{S}(\mathcal{M}) \coloneqq \left\{ Z \in \mathbb{S}^{n+1}_+ : \langle M, Z \rangle \le 0, \, \forall M \in \mathcal{M} \right\}$$

Well-known ROG sets:

• Positive semidefinite cone \mathbb{S}^{n+1}_+ itself!

$$\mathcal{S}(\mathcal{M}) \coloneqq \left\{ Z \in \mathbb{S}^{n+1}_+ : \langle M, Z \rangle \le 0, \, \forall M \in \mathcal{M} \right\}$$

Well-known ROG sets:

- Positive semidefinite cone \mathbb{S}^{n+1}_+ itself!
- Any single linear matrix inequality (LMI) or equation (LME):

$$\mathcal{S}(\mathcal{M}) \coloneqq \left\{ Z \in \mathbb{S}^{n+1}_+ : \langle M, Z \rangle \le 0, \, \forall M \in \mathcal{M} \right\}$$

Well-known ROG sets:

- Positive semidefinite cone \mathbb{S}^{n+1}_+ itself!
- Any single linear matrix inequality (LMI) or equation (LME):

Theorem (S-lemma)

 $\mathcal{S}(\{M\})$ for any $M \in \mathbb{S}^{n+1}$ is ROG.

[Fradkov and Yakubovich, 1979, Sturm and Zhang, 2003]

S-lemma

Corollary (Homogeneous S-lemma)

For any $M_{\text{obj}}, M \in \mathbb{S}^{n+1}$, we have

$$\inf_{z \in \mathbb{R}^{n+1}} \left\{ z^\top M_{\mathsf{obj}} z: \, z^\top M z \leq 0 \right\} \quad = \inf_{Z \in \mathbb{S}^{n+1}} \left\{ \langle M_{\mathsf{obj}}, Z \rangle: \, \langle M, Z \rangle \leq 0 \right\}$$

S-lemma

Corollary (Homogeneous S-lemma)

For any $M_{\text{obj}}, M \in \mathbb{S}^{n+1}$, we have

$$\inf_{z \in \mathbb{R}^{n+1}} \left\{ z^\top M_{\mathsf{obj}} z : \, z^\top M z \le 0 \right\} \quad = \inf_{Z \in \mathbb{S}^{n+1}} \left\{ \langle M_{\mathsf{obj}}, Z \rangle : \, \langle M, Z \rangle \le 0 \right\}$$

Equivalently, suppose $\exists \bar{z} \text{ s.t. } \bar{z}^\top M \bar{z} < 0$. Then,

$$\left[z^{\top}Mz \le 0 \implies z^{\top}M_{\mathsf{obj}}z \le 0 \right] \quad \text{iff} \quad \left[\exists \alpha \in \mathbb{R}_+ \text{ s.t. } \alpha M \succeq M_{\mathsf{obj}} \right]$$

S-lemma

Corollary (Homogeneous S-lemma)

For any $M_{\text{obj}}, M \in \mathbb{S}^{n+1}$, we have

$$\inf_{z \in \mathbb{R}^{n+1}} \left\{ z^\top M_{\mathsf{obj}} z : \, z^\top M z \le 0 \right\} \quad = \inf_{Z \in \mathbb{S}^{n+1}} \left\{ \langle M_{\mathsf{obj}}, Z \rangle : \, \langle M, Z \rangle \le 0 \right\}$$

Equivalently, suppose $\exists \bar{z} \text{ s.t. } \bar{z}^{\top} M \bar{z} < 0$. Then,

$$\begin{bmatrix} z^{\top}Mz \leq 0 \implies z^{\top}M_{\mathsf{obj}}z \leq 0 \end{bmatrix}$$
 iff $[\exists \alpha \in \mathbb{R}_+ \text{ s.t. } \alpha M \succeq M_{\mathsf{obj}}]$

Corollary (Inhomogeneous S-lemma)

For any $A_{obj}, A \in \mathbb{S}^n$, any $b_{obj}, b \in \mathbb{R}^n$ and $c \in \mathbb{R}$ s.t. $\exists \bar{x}$ satisfying $\bar{x}^\top A \bar{x} + b^\top \bar{x} + c < 0$ and $Opt > -\infty$, we have $Opt = \inf_{x \in \mathbb{R}^n} \left\{ x^\top A_{obj} x + b_{obj}^\top x : x^\top A x + b^\top x + c \le 0 \right\}$ $= \inf_{x \in \mathbb{R}^n, X \in \mathbb{S}^n} \left\{ \langle A_{obj}, X \rangle + b_{obj}^\top x : \langle A, X \rangle + b^\top x + c \le 0, \ X \succeq x x^\top \right\}.$

• Question: for what $\mathcal{M} \subseteq \mathbb{S}^{n+1}$ is $\mathcal{S}(\mathcal{M})$ ROG?

Thank you!

Questions?

References I

- Agler, J., Helton, W., McCullough, S., and Rodman, L. (1988). Positive semidefinite matrices with a given sparsity pattern. *Linear Algebra Appl.*, 107:101–149.
- Argue, C., K.-K., F., and Wang, A. L. (2022+). Necessary and sufficient conditions for rank-one generated cones. *Math. Oper. Res.*, Forthcoming, (arXiv:2007.07433).
- Ben-Tal, A. and Nemirovski, A. (2001). *Lectures on Modern Convex Optimization*, volume 2 of *MPS-SIAM Ser. Optim.* SIAM.
- Blekherman, G., Sinn, R., and Velasco, M. (2017). Do sums of squares dream of free resolutions? *SIAM J. Appl. Algebra Geom.*, 1:175–199.
- Burer, S. (2015). A gentle, geometric introduction to copositive optimization. *Math. Program.*, 151:89–116.
- Burer, S. (2023). A slightly lifted convex relaxation for nonconvex quadratic programming with ball constraints. *arXiv preprint arXiv:2303.01624*.
- Fradkov, A. L. and Yakubovich, V. A. (1979). The S-procedure and duality relations in nonconvex problems of quadratic programming. *Vestnik Leningrad Univ. Math.*, 6:101–109.
- Grone, R., Johnson, C. R., Sá, E. M., and Wolkowicz, H. (1984). Positive definite completions of partial Hermitian matrices. *Linear Algebra Appl.*, 58:109–124.

- Hildebrand, R. (2016). Spectrahedral cones generated by rank 1 matrices. *J. Global Optim.*, 64:349–397.
- K.-K., F. and Wang, A. L. (2021). Exactness in SDP relaxations of QCQPs: Theory and applications. Tut. in Oper. Res. INFORMS.
- Kelly, S., Ouyang, Y., and Yang, B. (2022). A note on semidefinite representable reformulations for two variants of the trust-region subproblem. *Manuscript, School of Mathematical and Statistical Sciences, Clemson University, Clemson, South Carolina, USA*.
- Laurent, M. and Poljak, S. (1995). On a positive semidefinite relaxation of the cut polytope. *Linear Algebra Appl.*, 223-224:439–461.
- Paulsen, V. I., Power, S. C., and Smith, R. R. (1989). Schur products and matrix completions. *J. Funct. Anal.*, 85(1):151–178.
- Sturm, J. F. and Zhang, S. (2003). On cones of nonnegative quadratic functions. *Math. Oper. Res.*, 28(2):246–267.
- Wang, A. L. and K.-K., F. (2022a). Accelerated first-order methods for a class of semidefinite programs. *arXiv preprint*, 2206.00224.

- Wang, A. L. and K.-K., F. (2022b). The generalized trust region subproblem: solution complexity and convex hull results. *Math. Program.*, 191:445–486.
- Wang, A. L. and K.-K., F. (2022c). On the tightness of SDP relaxations of QCQPs. *Math. Program.*, 193:33–73.
- Wang, A. L., Lu, Y., and K.-K., F. (2023+). Implicit regularity and linear convergence rates for the generalized trust-region subproblem. *SIAM J. Optim.*, Forthcoming, (arXiv:2112.13821).
- Yang, B., Anstreicher, K., and Burer, S. (2018). Quadratic programs with hollows. *Math. Program.*, 170:541–553.