# A fast combinatorial algorithm for the bilevel knapsack problem with interdiction constraints

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UNIVERSITY OF WATERLOO FACULTY OF MATHEMATICS Department of Combinatorics and Optimization Bilevel knapsack with interdiction constraints (BKP)

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- ▶ We are interested in solving this problem exactly
- ► Objective: win the horse race

**Given:** *n* items, weights  $w^U, w^L \in \mathbb{Z}_{\geq 0}^n$ , profits  $p \in \mathbb{Z}_{\geq 0}^n$ , capacities  $C^U, C^L \in \mathbb{Z}_{\geq 0}$ .

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• **Objective**: Select X to minimize the maximum profit the Follower can get

# Bilevel programming interpretation of BKP

**Given:** *n* items, weights  $w^U, w^L \in \mathbb{Z}_{\geq 0}^n$ , profits  $p \in \mathbb{Z}_{\geq 0}^n$ , capacities  $C^U, C^L \in \mathbb{Z}_{\geq 0}$ .

**Objective:** 
$$\min_{X \in \mathcal{U}} \max_{Y \in \mathcal{L}(X)} \sum_{i \in Y} p_i$$

where

$$\mathcal{U} = \left\{ X \subseteq \{1, \dots, n\} : \sum_{i \in X} w_i^U \le C^U \right\}$$
$$\mathcal{L}(X) = \left\{ Y \subseteq \{1, \dots, n\} \backslash X : \sum_{i \in Y} w_i^L \le C^L \right\}$$

(upper/leaders knapsack)

(lower/followers knapsack)

# Motivation: bilevel programming

BKP is a bilevel integer programming problem:

$$\begin{array}{ll} \min & c^T x + d^T y \\ \text{s.t.} & Ax \leq b \\ & x \in \mathbb{Z}^n \\ & y \in \arg \max \left\{ f^T y : Gx + Hy \leq g, y \in \mathbb{Z}^p \right\} \end{array}$$
(BIP)

y must be optimal for a second optimization problem (depending on x).

History and motivation: bilevel programming

Why bilevel?

- Competing parties (military, business)
- Semi-cooperating parties (federal and regional governments)
- A natural way to get harder versions of classical problems

Complexity of BKP (Caprara, Carvalho, Lodi and Woeginger, 2014)

- $\Sigma_2^p$ -complete
- no polysize IP formulation unless the polynomial hierarchy collapses
- no pseudopolynomial time algorithm unless P=NP

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- General bilevel solvers are far from the performance of problem-specific methods...

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However...

- ► BKP is perhaps one of the "easiest"  $\Sigma_2^p$ -complete problems
- General bilevel solvers are far from the performance of problem-specific methods...and this paper only widens that gap

- $\blacktriangleright$  DeNegre (2011) introduced the problem. Solved instances with  $\leq$  15 items
- $\blacktriangleright$  Caprara, Carvalho, Lodi and Woeginger (2016): Solved instances with  $\leq$  50 items
- > Tang, Richard and Smith (2016): Solved instances with  $\leq$  30 items
- Fischetti, Ljubic, Monaci, and Sinnl (2019). Solved instances with  $\leq$  55 items
- ▶ Lozano, Bergman and Cire (2022). Solved instances with  $\leq$  50 items
- ▶ Della Croce and Scatamacchia (2018). Solved instances with ≤ 500 items (henceforth the DCS algorithm)

... and more on approximation, complexity, problem variants, etc

Lower bounds and upper bounds



 $\blacktriangleright$  Feasible solution  $\implies$  upper bound

Lower bounds are harder: first published 2018 (DCS algorithm)

All previous exact algorithms use MIP solvers.

We present a combinatorial algorithm which outperforms the previous best method, the DCS algorithm.

Our key insight: a new way of relaxing bilevel problems.

#### Preliminaries

- ► X: upper level/leader's items
- ► Y: lower level/follower's items
- $\blacktriangleright$  Items are enumerated by  $\{1,\ldots,n\}$  and ordered such that

$$\frac{p_1}{w_1^L} \ge \frac{p_2}{w_2^L} \ge \cdots \ge \frac{p_n}{w_n^L}$$

# Branch and bound



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For node (X, i), is it possible that  $\exists X' \supseteq X$  and  $\exists Y' \in \mathcal{L}(X')$  with (X', Y') optimal? If not, there is no point to explore the children of (X, i). For node (X, i), is it possible that  $\exists X' \supseteq X$  and  $\exists Y' \in \mathcal{L}(X')$  with (X', Y') optimal? If not, there is no point to explore the children of (X, i).

To test this, we compute a lower bound at each node and test if it exceeds the current best upper bound.

## Lower bound

Consider a node (X, i). In all descendants (X', i') of (X, i), we have  $X' \supseteq X$  and i' > i. We want to lower bound the solution for such (X', i') which are leaves.

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We split this computation into two parts:

- 1. Lower bound using items  $\{1, \ldots, i-1\}$  (prefix)
- 2. Lower bound using items  $\{i, \ldots, n\}$  (postfix)

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Note that:

- ▶ We know that the Leader uses capacity  $\sum_{i \in X} w_i^U$  on the prefix
- This leaves  $C^U \sum_{i \in X} w_i^U$  for the postfix
- We don't know how much capacity the Follower uses on the prefix or the postfix, but any guess will give a lower bound.

Lower bound: items  $\{1, \ldots, i-1\}$  (prefix)

Given: Leader's items X, and (guessed) lower capacity  $c^{L}$ .

- X has already been decided on  $\{1, \ldots, i-1\}$
- So it suffices to find the optimal Y on items  $\{1, \ldots, i-1\} \setminus X$  with capacity  $c^L$
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#### Definition

Let K(S, c) denote the optimal objective value of the 0-1 knapsack problem with profits  $(p_i)_{i \in S}$ , weights  $(w_i^L)_{i \in S}$  and capacity c.

The desired bound is 
$$K(\{1,\ldots,i-1\}\setminus X,c^L)$$
.

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▶ Round 2i - 1: If  $w_i^U + \sum_{j \in X} w_j^U \leq c^U$ , Leader can add item *i* to X.



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▶ Round 2i: If  $i \notin X$  and  $w_i^L + \sum_{j \in Y} w_j^L \leq c^L$ , Follower can add item *i* to *Y*.

# What's changed? Intuition

- ► The Leader (minimizer) gets more information
- The Follower (maximizer) gets less information

Net result: a lower bound

# Solving the modified game

The modified game admits a pseudopolytime algorithm by dynamic programming:

#### Theorem

 $\omega(i, c^U, c^L)$  is the optimal objective value of the modified game when restricted to items  $\{i, \ldots, n\}$  with Leader's capacity  $c^U$  and Follower's capacity  $c^L$ .

# Postfix lower bound formalized

#### Definition

Let  $OPT(i, c^U, c^L)$  be the optimal objective value for BKP when restricted to items  $\{i, \ldots, n\}$  with Leader's capacity  $c^U$  and Follower's capacity  $c^L$ .

#### Theorem (Postfix lower bound)

For all  $i \in [n]$ ,  $0 \le c^U \le C^U$ , and  $0 \le c^L \le C^L$ , we have

 $\omega(i, c^U, c^L) \leq OPT(i, c^U, c^L).$ 

# Combining prefix and postfix

Let  $c \in [0, C^{L}]$  be a guess for how much capacity the Follower uses on the prefix. Recall:

- Prefix lower bound:  $K(\{1, \ldots, i-1\} \setminus X, c)$
- ▶ Postfix lower bound:  $\omega(i, C^U \sum_{j \in X} w_j^U, C^L c)$

#### Theorem

$$\mathcal{K}(\{1,\ldots,i-1\}\setminus X,c)+\omega(i,C^U-\sum_{j\in X}w_j^U,C^L-c)$$

is a lower bound for node (X, i), and it can be computed in pseudopolynomial time.

# Extensions & improvements: Solving trivial instances faster

Our lower bound is expensive: it requires pseudopolynomial time and memory. Can we avoid computing it? Our lower bound is expensive: it requires pseudopolynomial time and memory.

Can we avoid computing it?

<u>Sometimes!</u> Can get a much weaker lower bound in polytime by solving a linear program inspired by the DCS algorithm. Using this and a greedy upper bound, we can detect and solve trivial instances near instantly.

Extensions & improvements: sparse DP tables

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Can we compute less of it?

Yes! We can use sparse dynamic programming tables, like the classical DP-with-lists approach for knapsack.

This makes it practical to solve instances with arbitrarily large capacity.

# Extensions & improvements: generalizations

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Yes! Easy to generalize to:

- Bounded knapsack problem
- Multidimensional knapsack problem
- Min-max regret knapsack problem
- ... hopefully many more

### Implementation

- ▶ We implemented the algorithm in C++
- We reimplemented the DCS algorithm in C++ with Gurobi; our reimplementation generally matches or exceeds the performance of the original implementation
- DCS is parallelized via Gurobi
- ▶ In our algorithm, only the dynamic programming is parallelized
- ▶ We test on all instances from the literature, and generate some more

# Computational results

Selected instances: generated by Fischetti, Monaci and Sinnl (2018), with n up to 500 and capacity up to 25000.

	DCS			$\operatorname{Comb}$				
Class	#Opt	#Best	Avg	Max	# Opt	#Best	Avg	$\operatorname{Max}$
uncorrelated	50	0	3.66	13.38	50	50	0.64	7.1
weak correlated	50	0	13.49	72.64	50	50	0.39	4.76
strong correlated <sup>*</sup>	41	0	689.58	$3,\!600$	50	50	0.46	5.02
inverse strong corr.*	38	0	919.91	$3,\!600$	50	50	1.17	31.11
almost strong corr. $*$	40	0	815.4	$3,\!600$	50	50	0.35	4.28
subset-sum*	35	0	1,087.18	$3,\!600$	42	42	588.57	$3,\!600$
$even-odd subset-sum^*$	36	0	1,033.98	$3,\!600$	42	42	582.37	3,600
even-odd strong corr.*	41	0	747.12	$3,\!600$	50	50	0.73	17.06
similar weight uncorr.	50	0	22.89	79.85	50	50	0.12	0.35

#### (Running times in seconds)

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# Performance profile: all instances from the literature



# Lower bound strength in practice vs theory

- The relaxed game is optimal for BKP on 85% of instances
- There is a (contrived) family of instances where it has gap O(n):

item no.	р	w <sup>U</sup>	w <sup>L</sup>
1	1	1	1
2	2	2	2
÷	÷	÷	÷
n-1	n-1	n-1	n-1
п	$\binom{n}{2}$	$\binom{n}{2}$	$\binom{n}{2} + 1$

But with branch-and-bound, we solve this family near instantly



# Conclusion

- Our solver has better performance on 99% of instances
- ▶ We solved 74% of the unsolved instances in the literature
- Key takeaway: relax the bilevel problem to 2n alternating levels: this gives a strong lower bound

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#### Future work / Open problems

- Is there a "fast" algorithm for subset-sum instances?
- What other problems would benefit from this type of relaxation?
- What can be said, theoretically, about the performance of our algorithm on particular instance classes?

Thanks for your attention!