

Decomposition of Probability Marginals for Security Games in Abstract Networks (and Ideal Clutters)

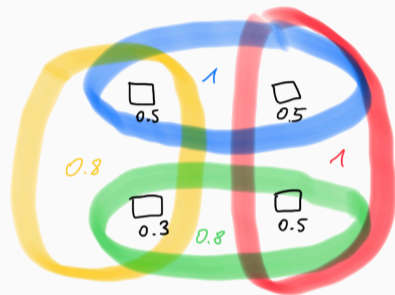
Jannik Matuschke

KU Leuven

From Marginals to Distributions

Input:

- ground set E
- set system $\mathcal{P} \subseteq 2^E$
- requirements $\pi \in [0, 1]^{\mathcal{P}}$
- marginals $\rho \in [0, 1]^E$



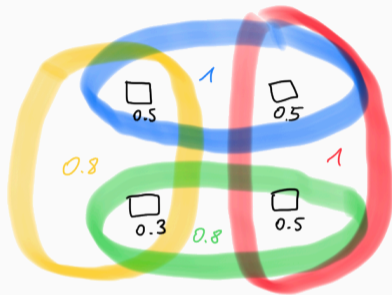
From Marginals to Distributions

Input:

- ground set E
- set system $\mathcal{P} \subseteq 2^E$
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Goal: Find distribution for random set $S \subseteq E$ such that

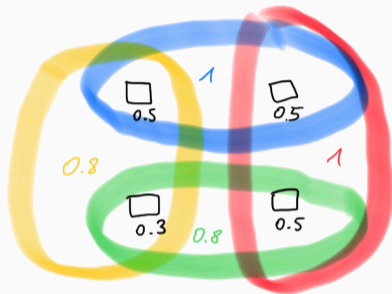
$$\Pr[e \in S] = \rho_e \quad \forall e \in E,$$
$$\Pr[P \cap S \neq \emptyset] \geq \pi_P \quad \forall P \in \mathcal{P}.$$



A Necessary Condition

All feasible marginals ρ must fulfil:

$$\sum_{e \in P} \rho_e \geq \pi_P \quad \forall P \in \mathcal{P} \quad (\star)$$

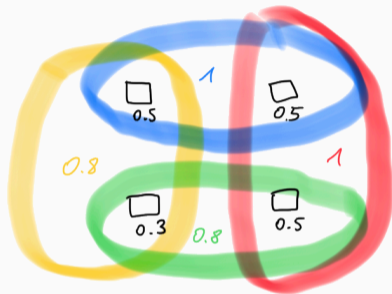


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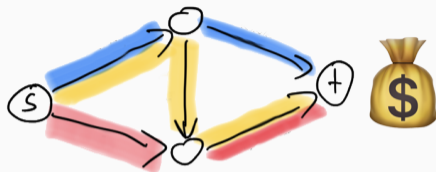
All feasible marginals ρ must fulfil:

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For which systems (\mathcal{P}, π) is (\star) also sufficient?



Motivation: A Security Game



c_e : inspection cost

π_P : risk threshold

Inspect random set $S \subseteq E$:

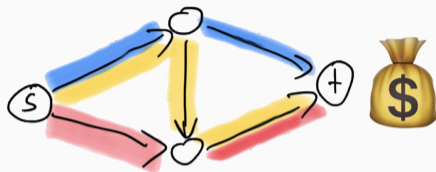
$$\min \sum_{S \subseteq E} \sum_{e \in S} c_e x_S$$

$$\text{s.t. } \sum_{S: P \cap S \neq \emptyset} x_S \geq \pi_P \quad \forall P \in \mathcal{P}$$

$$\sum_{S \subseteq E} x_S = 1$$

$$x \geq 0$$

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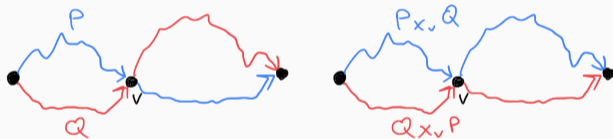
If (\star) is sufficient:

$$\begin{aligned} \min \quad & \sum_{e \in E} c_e \rho_e \\ \text{s.t.} \quad & \sum_{e \in P} \rho_e \geq \pi_P \quad \forall P \in \mathcal{P} \\ & \rho \in [0, 1]^E \end{aligned}$$

$\mathcal{P} = \{s-t\text{-paths in a DAG}\}$, two settings for π :

(A) Affine requirements: $\pi_P = 1 - \sum_{e \in P} \mu_e$ for some $\mu \in [0, 1]^E$

(C) Conservation law: $\pi_P + \pi_Q = \pi_{P \times_v Q} + \pi_{Q \times_v P}$ for $P, Q \in \mathcal{P}, v \in P \cap Q$

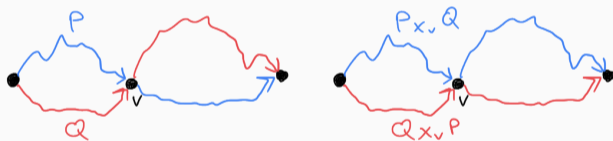


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Note: (A) \Rightarrow (C).

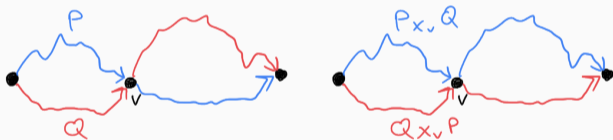


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Their results:

- For (C): (\star) is sufficient.
- For (A): Decomposition can be computed efficiently.
- Consequence: Computation of Nash equilibria for security game on DAG.

DAGs

(Dahan et al.)

Affine efficient algorithm

Conservation

(★) sufficient

(exp.-time algorithm)

New Results

DAGs

(Dahan et al.)

Abstract Networks

(incl. digraphs w. cycles)

Affine efficient algorithm

efficient algorithm

(explicit description) \oplus

Conservation

(\star) sufficient

(exp.-time algorithm)

\oplus combinatorial shortest-path algorithm for abstract networks

New Results



⊕ combinatorial shortest-path algorithm for abstract networks

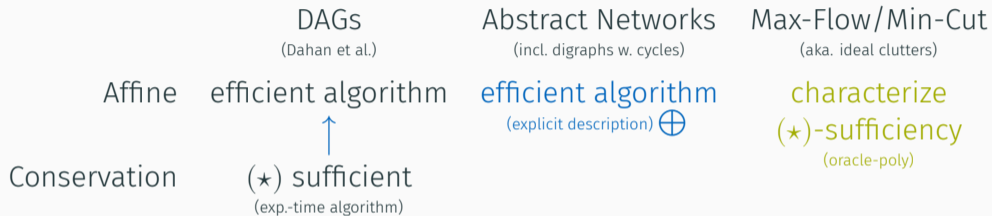
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Also: NP-hard to decide feasibility of given ρ in general systems

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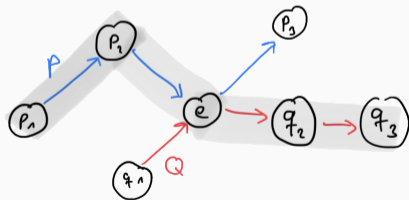
Also: NP-hard to decide feasibility of given ρ in general systems

Feasible Decompositions in Abstract Networks

Abstract network:

- set system (E, \mathcal{P})
- order \preceq_P for every $P \in \mathcal{P}$
- for every $P, Q \in \mathcal{P}$ and $e \in P \cap Q$:

$P \times_e Q \in \mathcal{P}$ contained in $\{p \in P : p \preceq_P e\} \cup \{q \in Q : e \preceq_Q q\}$.



$$P \times_e Q = q_3 \rightarrow p_2 \rightarrow q_2$$

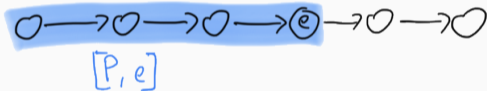
$$\sum_{e \in P} \rho_e \geq \pi_P \quad \forall P \in \mathcal{P} \quad (\star)$$

Construct random $S \subseteq E$ with

$$\Pr[e \in S] = \rho_e \quad \forall e \in E,$$

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$$\alpha_e := \min_{P \in \mathcal{P}} \sum_{f \in [P, e]} \rho_f + \mu_f$$



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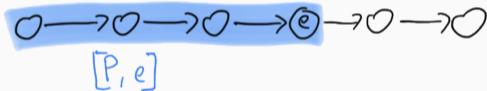
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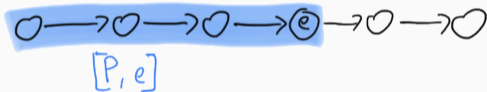
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Theorem. S_τ is a feasible decomposition of ρ .

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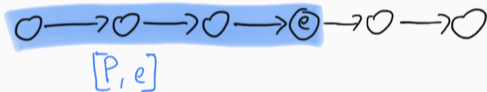
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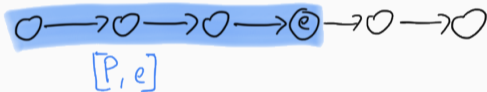
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By (\star) : $\alpha_t \geq 1$ for last element t of P

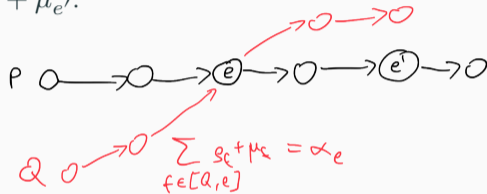
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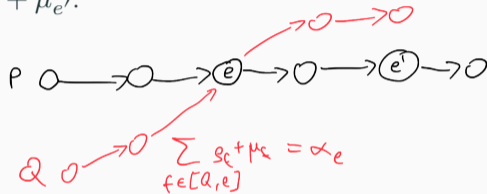
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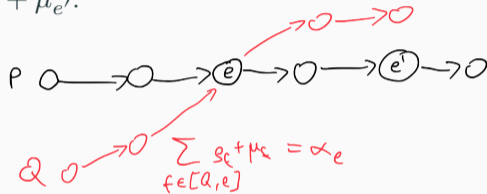


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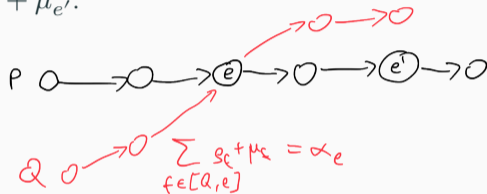
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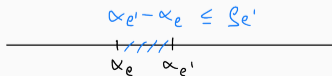
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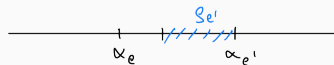
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Case 1:



Case 2:



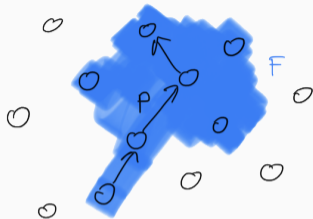
Shortest Paths in Abstract Networks

How Do We Access Abstract Networks?

Membership oracle for an abstract network:

Given $F \subseteq E$, either

- return $P \in \mathcal{P}$ (and \preceq_P) with $P \subseteq F$,
- or assert that no such P exists.

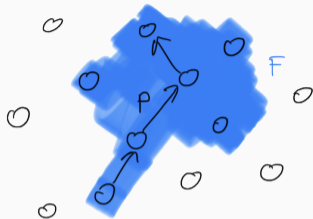


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McCormick (SODA 1996):

- Combinatorial algorithm for MAX FLOW in abstract networks using membership oracle (weakly poly-time).
- Strongly poly-time possible using stronger oracle?
E.g., shortest-path oracle?

Shortest Paths in Abstract Networks

Given: abstract network (E, \mathcal{P}) , costs $c \in \mathbb{R}_+^E$

Task: find $P \in \mathcal{P}$ minimizing $c(P) := \sum_{e \in P} c_e$

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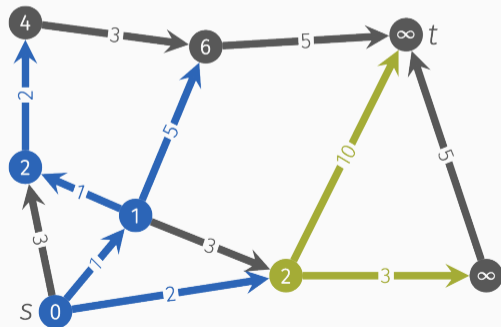


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Dijkstra's Algorithm



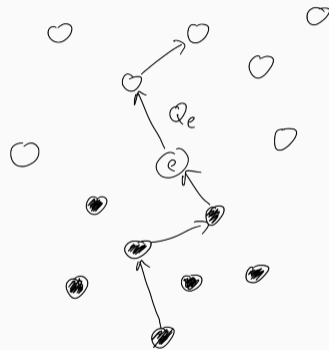
labels ϕ_e

paths Q_e

$$\phi_e = \sum_{f \in [Q_e, e]} c_f$$

Processing Elements

How to find all relevant ways to continue $[Q_e, e]$?

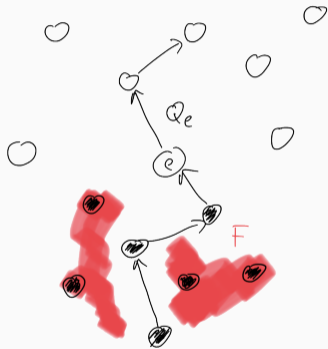


Processing Elements

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`process(e)`

- $F := T \setminus [Q_e, e]$

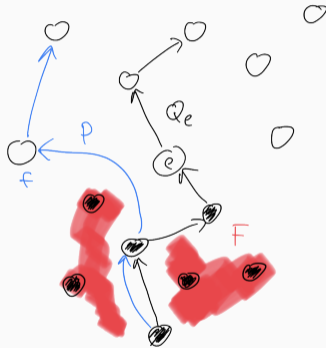


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 - if $c([P, f]) < \phi_f$ then update ϕ_f and Q_f

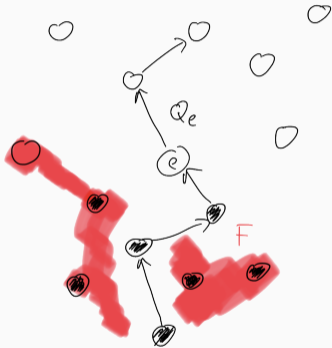


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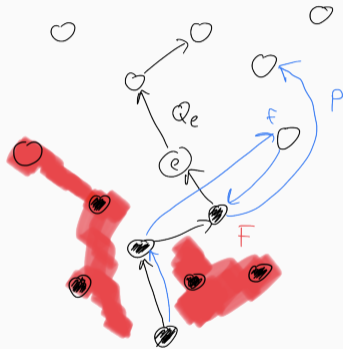


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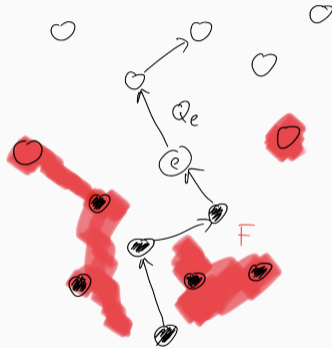


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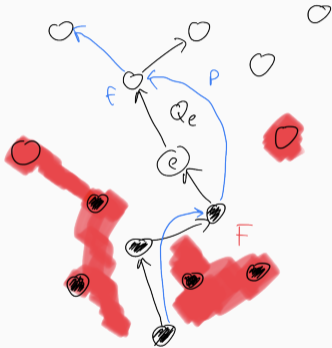


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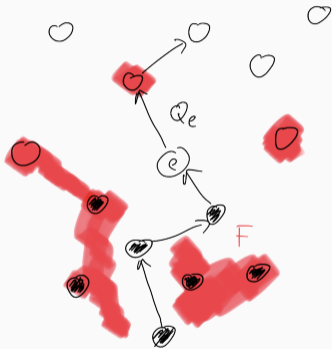


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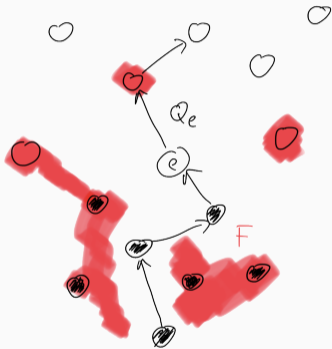
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Lemma. After **process**(e), for every $P \in \mathcal{P}$ with $e \in P$:

- there is $f \in P \setminus T$ with $\phi_f \leq \phi_e + c_f$.



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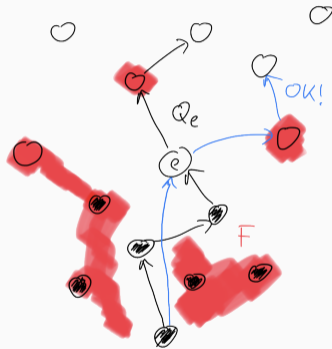
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- there is $f \in P \setminus T$ with $\phi_f \leq \phi_e + c_f$.



Processing Elements

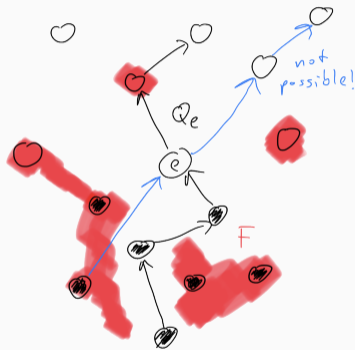
How to find all relevant ways to continue $[Q_e, e]$?

process(e)

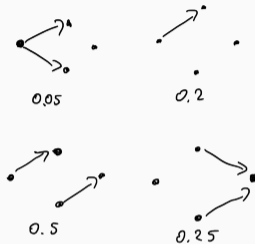
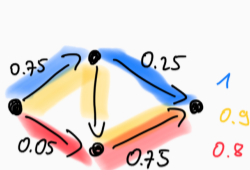
- $F := T \setminus [Q_e, e]$
- while $\exists P \in \mathcal{P}$ with $P \subseteq E \setminus F$:
 - $f := \min_{\leq_P} P \setminus [Q_e, e]$
 - $F := F \cup \{f\}$
 - if $c([P, f]) < \phi_f$ then update ϕ_f and Q_f
- $T := T \cup \{e\}$

Lemma. After **process**(e), for every $P \in \mathcal{P}$ with $e \in P$:

- there is $f \in P \setminus T$ with $\phi_f \leq \phi_e + c_f$.



Conclusion



- **(★)-sufficiency** allows formulating problems via their marginals:

$$\sum_{e \in P} \rho_e \geq \pi_P \quad \forall P \in \mathcal{P} \quad (\star)$$

- many systems are (★)-sufficient, including **abstract networks**
- feasible decompositions can be computed via a **shortest-path algorithm**

Overview & Open Questions

| | DAGs (Dahan et al.) | Abstract Networks (incl. digraphs w. cycles) | Max-Flow/Min-Cut |
|--------------|---|--|---|
| Affine | efficient algorithm | efficient algorithm (explicit description) \oplus | characterize (\star)-sufficiency |
| Conservation | (\star)-sufficient (exp.-time algorithm) | (\star)-sufficient (oracle-poly) | TDI systems? |

\oplus combinatorial shortest-path algorithm for abstract networks

Strongly poly-time algorithm for Abstract Max Flow?

Also: NP-hard to decide feasibility of given ρ in general systems

Poly-time algorithms for some non-(\star)-sufficient systems?

(\star)-sufficiency under additional constraints on decomposition?



“Portrait of Edsger W. Dijkstra, one of the greatest mathematicians in history of modern mathematics.” ©2002 Hamilton Richards

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