

Information complexity of mixed-integer convex optimization

Phillip Kerger

Work with Amitabh Basu, Hongyi Jiang, and Marco Molinaro



June 2023, IPCO

- 1 Introduction
 - Setting and Goals
 - Oracles Using First-Order Information

- 2 Selected Results and Proof Ideas
 - Lower Bounds
 - Upper Bounds

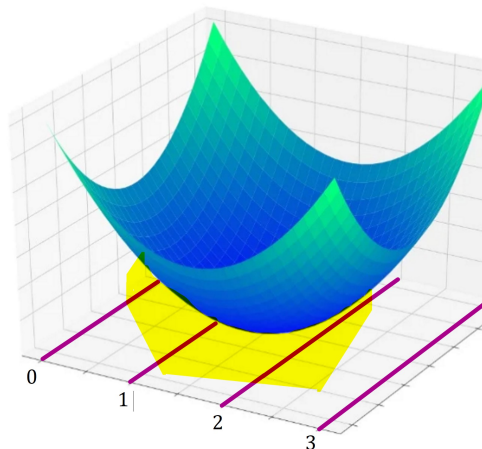
- 1 Introduction
 - Setting and Goals
 - Oracles Using First-Order Information

- 2 Selected Results and Proof Ideas
 - Lower Bounds
 - Upper Bounds

Mixed-integer convex optimization:

Min $f(x; y) : \mathbb{R}^{n+d} \rightarrow \mathbb{R}$ with

- f convex (possibly nonsmooth)
- $x \in \mathbb{Z}^n; y \in \mathbb{R}^d$
- $(x; y) \in C \subseteq \mathbb{R}^{n+d}$,
 C a convex set



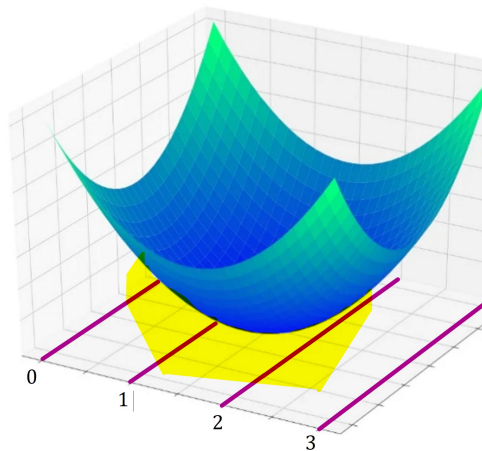
Mixed-integer convex optimization:

Can't solve this exactly!

) Only ask for "solution:

Feasible point

$(x; y) : f(x; y) \leq OPT_f$ ".



Mixed-integer convex optimization:

Can't solve this exactly!

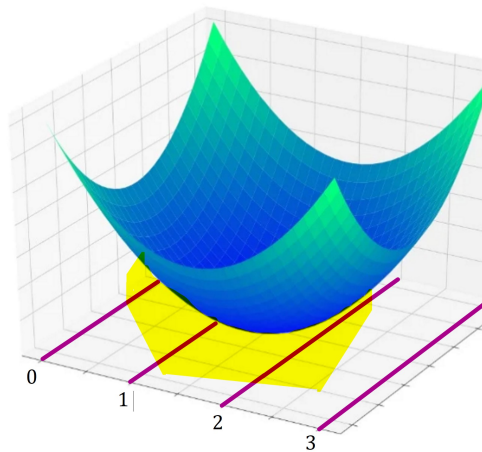
) Only ask for "ε-solution:

Feasible point

$(x; y) : f(x; y) \leq OPT_f + \epsilon$ "

But if ϵ is tiny...

there is also a problem



Parameterize the instances:

Definition

$I_{n;d;R;M}$ is the set of all MICO instances such that

- (i) C is a subset of the box $[-R; R]^{n+d}$.
- (ii) Fiber containing optimum isn't degenerate, but a ball of size ϵ in it is feasible.
- (iii) f is M -Lipschitz

Information Complexity:

How much information is needed to solve a problem?

Information Complexity:

How much information is needed to solve a problem?

Classical First-Order:

How many (exact) evaluations of function value and gradient or separating hyperplanes?

Information Complexity:

How much information is needed to solve a problem?

Classical First-Order:

How many (exact) evaluations of function value and gradient or separating hyperplanes?

Notice: Gradient length grows with dimension...

Information Complexity:

How much information is needed to solve a problem?

Classical First-Order:

How many (exact) evaluations of function value and gradient or separating hyperplanes?

Notice: Gradient length grows with dimension...

Gives **more information with dimension!**

Can we refine this in a meaningful way?

Information Complexity:

How much information is needed to solve a problem?

Classical First-Order:

How many (exact) evaluations of function value and gradient or separating hyperplanes?

Notice: Gradient length grows with dimension...

Gives **more information with dimension!**

Can we refine this in a meaningful way?

Goals of this work:

- Study information complexity beyond exact first-order model
- Tighten and generalize existing bounds

What kinds of oracles?

What kinds of oracles?

Definition

An *oracle using first-order information* consists of two parts:

What kinds of oracles?

Definition

An *oracle using first-order information* consists of two parts:

- 1 For each point $\mathbf{z} \in \mathbb{R}^{n+d}$, a map $g_{\mathbf{z}}$ that maps instances to first-order information at \mathbf{z} :
 - Function value and gradient (objective)
 - Feasibility flag and separating hyperplane (feasibility)
 - A collection of these for all \mathbf{z} : “First order chart” G

What kinds of oracles?

Definition

An *oracle using first-order information* consists of two parts:

- 1 For each point $\mathbf{z} \in \mathbb{R}^{n+d}$, a map $g_{\mathbf{z}}$ that maps instances to first-order information at \mathbf{z} :
 - Function value and gradient (objective)
 - Feasibility flag and separating hyperplane (feasibility)
 - A collection of these for all \mathbf{z} : “First order chart” G

What kinds of oracles?

Definition

An *oracle using first-order information* consists of two parts:

- 1 For each point $\mathbf{z} \in \mathbb{R}^{n+d}$, a map $g_{\mathbf{z}}$ that maps instances to first-order information at \mathbf{z} :
 - Function value and gradient (objective)
 - Feasibility flag and separating hyperplane (feasibility)
 - A collection of these for all \mathbf{z} : “First order chart” G
- 2 A set of *permissible queries* H
 $h \in H$ functions taking first order information as input.

What kinds of oracles?

Definition

An *oracle using first-order information* consists of two parts:

- 1 For each point $\mathbf{z} \in \mathbb{R}^{n+d}$, a map $g_{\mathbf{z}}$ that maps instances to first-order information at \mathbf{z} :
 - Function value and gradient (objective)
 - Feasibility flag and separating hyperplane (feasibility)
 - A collection of these for all \mathbf{z} : “First order chart” G
- 2 A set of *permissible queries* H
 $h \in H$ functions taking first order information as input.

What kinds of oracles?

Definition

An *oracle using first-order information* consists of two parts:

- 1 For each point $\mathbf{z} \in \mathbb{R}^{n+d}$, a map $g_{\mathbf{z}}$ that maps instances to first-order information at \mathbf{z} :
 - Function value and gradient (objective)
 - Feasibility flag and separating hyperplane (feasibility)
 - A collection of these for all \mathbf{z} : “First order chart” G
- 2 A set of *permissible queries* H
 $h \in H$ functions taking first order information as input.

For query h at \mathbf{z} , for instance J , oracle answers $h(g_{\mathbf{z}}(J))$

! Pair $(G; H)$ defines an oracle!

Oracles Using First-Order Information

Oracles Using First-Order Information

Large class of oracles with answers using only first-order info

Examples: Oracles Using First-Order Information

What kinds of oracles can we get?

Standard first-order oracle : H has only the identity

Examples: Oracles Using First-Order Information

What kinds of oracles can we get?

Standard first-order oracle : H has only the identity

Bit Queries : H output some designated bits of the function value/gradient/sep. hyperplane.

! How many bits of information does one need?

Examples: Oracles Using First-Order Information

What kinds of oracles can we get?

Standard first-order oracle : H has only the identity

Bit Queries : H output some designated bits of the function value/gradient/sep. hyperplane.

! How many bits of information does one need?

Directional Queries : Elements of H give the sign of the inner product of the gradient/sep. hyperplane with a vector $h_v = \text{sign}(v; g_z)$.

What kinds of oracles can we get?

- **Standard first-order oracle:** H has only the identity
- **Bit Queries:** H output some designated bits of the function value/gradient/sep. hyperplane.
*! How many **bits** of information does one need?*
- **Directional Queries:** Elements of H give the sign of the inner product of the gradient/sep. hyperplane with a vector $h_v = \text{sign} h_v; g_z i.$
- **General Binary Queries:** Let H contain all binary queries

- 1 Introduction
 - Setting and Goals
 - Oracles Using First-Order Information

- 2 Selected Results and Proof Ideas
 - Lower Bounds
 - Upper Bounds

Theorem (Lower-Bound for Standard Oracle)

$$\text{icomp} = \Omega \left(2^n d \log \frac{MR}{\epsilon} \right) :$$

$$\text{icomp} = 2^n \log \frac{MR}{\epsilon} :$$

Improvement on existing best bound (by incorporating ϵ).

$$\text{icomp} = 2^n \log \frac{MR}{n} :$$

Improvement on existing best bound (by incorporating M, R).
Presents a "transfer" of continuous case LB to MICO

How to think about these lower-bounds...

Lower Bounds

How to think about these lower-bounds...

Some continuous instance on each integer ber:

How to think about these lower-bounds...
Some continuous instance on each integer fiber:

In unit cube, 2^n means you need to solve all of them.

Theorem (Lower-Bound for Standard Oracle)

$$\text{icomp} = \Omega \left(2^n d \log \frac{MR}{\epsilon} \right) :$$

- Improvement on existing best bound by incorporating $M; \epsilon$.
- Presents a 2^n “transfer” of continuous case LB to MICO.

Theorem (Lower-Bound for Standard Oracle)

$$\text{icomp} = \Omega \left(2^n d \log \frac{MR}{\epsilon} \right) :$$

- Improvement on existing best bound by incorporating $M; \epsilon$.
- Presents a 2^n “transfer” of continuous case LB to MICO.

Conjecture (Transferring Lower-Bounds from Continuous to Mixed)

- Oracle $(G; H)$ using first-order info
- A family of instances with a lower bound $\Omega(d; R; \epsilon; M)$ for the continuous case with this oracle

Then there exist a family of instances with lower-bound $\Omega(d; R; \epsilon; M)$ for the general MICO case.

Conjecture proven for pure optimization case!

Proof idea for optimization case of conjecture:

- "Place" one continuous instance on each integer fiber $\mathbf{x} \in \mathbb{R}^d$,
 $\mathbf{x} \in \{0, 1\}^n$.

Lower Bounds

Proof idea for optimization case of conjecture:

- "Place" one continuous instance on each integer fiber $\mathbf{x} \in \mathbb{R}^d$, $\mathbf{x} \in [0; 1]^n$.
- Want: No query in the full space to give more information than a query on one of the fiber functions

Proof idea for optimization case of conjecture:

- "Place" one continuous instance on each integer fiber $\mathbf{x} \in \mathbb{R}^d$, $\mathbf{x} \in [0; 1]^n$.
- Want: No query in the full space to give more information than a query on one of the fiber functions
! Extend the fiber functions to \mathbb{R}^{n+d} such that any query not on a fiber can be simulated by a query on a fiber

Proof idea for optimization case of conjecture:

- "Place" one continuous instance on each integer fiber $\mathbf{x} \in \mathbb{R}^d$, $\mathbf{x} \in [0; 1]^n$.
- Want: No query in the full space to give more information than a query on one of the fiber functions
! Extend the fiber functions to \mathbb{R}^{n+d} such that any query not on a fiber can be simulated by a query on a fiber

Construction:

Theorem

If H contains only binary functions, with access to oracle $(G; H)$

$$\text{icomp} = \tilde{\Omega} \left(d^{\frac{8}{7}} \right) :$$

Theorem

If H contains only binary functions, with access to oracle $(G; H)$

$$\text{icomp} = \tilde{\Omega} \left(d^{\frac{8}{7}} \right) :$$

Uses ideas from recent results on memory-constrained algorithms.

Upper Bounds ($n = 0$ case)

Theorem

- Instances with function values in $[-U; U]$
- Permissible queries H are the bit or directional sign queries

$$\text{icomp} = O \left(d^2 \log^2 \frac{dMR}{\epsilon} \log \frac{U}{\epsilon} \right)$$

Upper Bounds ($n = 0$ case)

Theorem

- Instances with function values in $[U; U]$
- Permissible queries H are the bit or directional sign queries

$$\text{icomp} = O \left(d^2 \log^2 \frac{dMR}{\epsilon} \log \frac{U}{\epsilon} \right)$$

Roughly LB under *exact* oracle times $d \log \left(\frac{dMR}{\epsilon} \right)$

"-approximate gradient contains roughly $d \log \left(\frac{1}{\epsilon} \right)$ bits

Conjecture ("The above upper-bound is good")

When permissible queries H are binary functions,

$$\text{icomp} = \Omega \left(d^2 \log \frac{MR}{\epsilon} \right)^2$$

Theorem (Similar result in the general MICO case)

For the general MICO case with binary permissible queries H ,

$$\text{icomp} = O \left(2^n d (n + d)^2 \log^2 \frac{dMR}{\min f ; 1g''} \right)$$

Theorem

- **Finitely many instances** $I = I_{n;d;R; ;M}$
- H for the oracle consisting of all binary functions

$$icomp = O \left(\log |J| + d \log \frac{MR}{\epsilon} \right)$$

Compare to:

$\tilde{\Omega} d^{\frac{8}{7}}$ lower-bound

$\Omega d^2 \log \frac{MR}{\epsilon}^2$ conjectured lower-bound

Upper Bounds

Proof idea for feasibility case:

Maintain a family $\mathcal{U} \subseteq \mathcal{I}$ of the instances that are possible, and a polyhedron P containing C .

Start with $\mathcal{U} = \mathcal{I}$ and $P = [-R; R]^d$.

We will be able to either **reduce** $|\mathcal{U}|$ or $\text{vol}(P)$ by a **constant fraction** with each query.

Upper Bounds

Proof idea for feasibility case:

Maintain a family $U \subseteq I$ of the instances that are possible, and a polyhedron P containing C .

Start with $U = I$ and $P = [-R; R]^d$.

We will be able to either reduce $|U|$ or $\text{vol}(P)$ by a constant fraction with each query.

While $|U| > 1$ do the following:

Set p equal to be the centroid of P . If the separation oracle at p reports that $p \notin C$, then we return p .

Otherwise...

Upper Bounds

Case 1: For all v , no more than half the instances $\mathcal{C} \subseteq 2^U$ give the answer $\mathbb{g}_p^{\text{sep}}(\mathcal{C}^0) = v$.

Upper Bounds

Case 1: For all v , no more than half the instances $\mathcal{C} \subseteq 2^U$ give the answer $\mathbb{g}_p^{\text{sep}}(\mathcal{C}^0) = v$.

) there is a set of answers $\mathcal{M} \subseteq \mathbb{R}^d$ such that between $\frac{1}{4}|U|$ and $\frac{3}{4}|U|$ of the sets give an answer \mathcal{M} .

Upper Bounds

Case 1: For all v , no more than half the instances $C \in \mathcal{C}^0 \subseteq 2^U$ give the answer \mathbb{R}^d .
 \mathbb{R}^d $\text{opt}^{\text{sep}}(C^0) = v$.

) there is a set of answers $M \subseteq \mathbb{R}^d$ such that between $\frac{1}{4}|U|$ and $\frac{3}{4}|U|$ of the sets give an answer in M .

Query whether the true instance has $\text{opt}^{\text{sep}}(C) \in V$.

) Size of U decreases by at least $\frac{1}{4}$.

Upper Bounds

Case 1: For all v , no more than half the instances $C \in \mathcal{C} \cap U$ give the answer $\mathbb{Q}_p^{\text{sep}}(C) = v$.

) there is a set of answers $M \subseteq \mathbb{R}^d$ such that between $\frac{1}{4}|U|$ and $\frac{3}{4}|U|$ of the sets give an answer in M .

Query whether the true instance has $\mathbb{Q}_p^{\text{sep}}(C) \in V$.

) Size of U decreases by at least $\frac{1}{4}$.

Case 2: There exists $v \in \mathbb{R}^d$ such that more than half of the instances have $\mathbb{Q}_p^{\text{sep}}(C) = v$.

Upper Bounds

Case 1: For all v , no more than half the instances $\mathcal{C} \cap U$ give the answer $g_p^{\text{sep}}(\mathcal{C}) = v$.

) there is a set of answers $M \subset \mathbb{R}^d$ such that between $\frac{1}{4}|U|$ and $\frac{3}{4}|U|$ of the sets give an answer in M .

Query whether the true instance has $g_p^{\text{sep}}(\mathcal{C}) \in V$.

) Size of U decreases by at least $\frac{1}{4}$.

Case 2: There exists $v \in \mathbb{R}^d$ such that more than half of the instances have $g_p^{\text{sep}}(\mathcal{C}) = v$.

Query whether the true instance has $g_p^{\text{sep}}(\mathcal{C}) = v$.

) Either size of U decreases by at least half, or we get an exact separating hyperplane for the true instance to reduce the volume of P by at least $1 - \epsilon$ (Grünbaum's theorem).

Upper Bounds

Case 1: For all v , no more than half the instances $\mathcal{C} \cap 2U$ give the answer $g_p^{sep}(\mathcal{C}) = v$.

) there is a set of answers $M \subset \mathbb{R}^d$ such that between $\frac{1}{4}|U|$ and $\frac{3}{4}|U|$ of the sets give an answer in M .

Query whether the true instance has $g_p^{sep}(\mathcal{C}) \in V$.

) Size of U decreases by at least $\frac{1}{4}$.

Case 2: There exists $v \in \mathbb{R}^d$ such that more than half of the instances have $g_p^{sep}(\mathcal{C}) = v$.

Query whether the true instance has $g_p^{sep}(\mathcal{C}) = v$.

) Either size of U decreases by at least half, or we get an exact separating hyperplane for the true instance to reduce the volume of P by at least $\frac{1}{e}$ (Grünbaum's theorem).

Reducing U can only happen $\log(j)$ times, and reducing the volume of P can only happen $\log\left(\frac{MR}{\min_i g_i^n}\right)$ times.

Thank you for your attention!

Questions?