ReLU Neural Networks of Polynomial Size for Exact Maximum Flow Computation

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Neural Networks in Action



Krizhevsky et al. "Imagenet classification with deep convolutional neural networks" (NeurIPS 2012)

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Gatys et al. "Image style transfer using convolutional neural networks" (CVPR 2016)



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DeepL Translator DeepL Pro	Why DeepL? Login
Translate text 26 languages I pdf, doox, pptx	
German (detected) 🗸	English (UK) V Glossary
Das Pferd frisst × keinen Gurkensalat.	The horse does not eat cucumber salad.

Screenshot deepl.com (Feb 18, 2022)

A Single ReLU Neuron



A Single ReLU Neuron



Rectified linear unit (ReLU): $relu(x) = max\{0, x\}$





Image created with GeoGebra (geogebra.org)

ReLU Feedforward Neural Networks

Acyclic (layered) digraph of ReLU neurons



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Computes function

$$T_k \circ \operatorname{relu} \circ T_{k-1} \circ \cdots \circ T_2 \circ \operatorname{relu} \circ T_1$$

with affine transformations T_i .

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Example: Computing the Maximum of Two Numbers

$$\max\{x, y\} = \max\{x - y, 0\} + y$$



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Example: Computing the Maximum of Four Numbers



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 Inductively: Max of n numbers with depth O(log n) and size O(n).

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Minimum similarly.

Representing Arbitrary Piecewise Linear Functions

Observation

Every function represented by a ReLU NN is continuous and piecewise linear (CPWL).

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1. Is logarithmic depth best possible?

2. Which functions can we represent with polynomial size?

Our Results



Our Results





Neural Networks as Model of Real-Valued Computation

Neural Networks as Model of Real-Valued Computation

Neural Networks

Arithmetic circuits with (weighted) sums and maxima gates

Neural Networks as Model of **Real-Valued** Computation

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Polynomial-Size NNs



Strongly polynomial algorithms with restricted set of operations

Input: $x, y \in \mathbb{R}$ $v_1 = x - y$ $v_2 = \max\{0, v_1\}$ $m = v_2 + y$ return m.

Why Edmonds-Karp does not work



Assume *s*-*t*-distance of length $\geq k$ in residual network. Need to find an augmenting *s*-*t*-flow which

- uses only arcs along paths of length k,
- is feasible in the residual network, and
- saturates at least one arc (if distance = k).

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Then: Similar analysis to Edmonds-Karp

1. Compute fattest path values $a_{i,v}$: maximum amount of flow that can be pushed on a single path of length exactly *i* from *v* to *t*:

$$a_{i,v} = \max_{vw \in E} \{\min\{c_{vw}, a_{i-1,w}\}\}$$

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- 2. Push greedily flow from s to t, while ensuring that in *i*-th pushing phase flow arriving at v does not exceed $a_{k-i,v}$.
- 3. Clean-up to restore flow conservation.





push phase; after i = 4







push phase; after i = 3







push phase; after i = 1





clean-up; after i = 2





clean-up; after i = 3









Hertrich, Sering (IPCO 2023)



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- Mininum Cost Flows, Matchings, general LPs?
- Are there CPWL functions computable in strongly polynomial time which are not representable by poly-size NNs?
- Might extended formulations help?